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## RESULTS OF AN EXPERIMENTAL INVESTIGATION OF THE PERFORMANCE OF AN EXPANSION TUBE

By

Glenn D. Norfleet, John J. Lacey, Jr.,  
and Jack D. Whitfield  
ARO, Inc.

PL

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OF THE PERFORMANCE OF AN EXPANSION TUBE

Glenn D. Norfleet, John J. Lacey, Jr.,  
and Jack D. Whitfield  
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## FOREWORD

The research reported herein was done by ARO, Inc. (a subsidiary of Sverdrup and Parcel, Inc.), contract operator of the Arnold Engineering Development Center (AEDC), Air Force Systems Command (AFSC), Arnold Air Force Station, Tennessee, under Contract AF 40(600)-1200. The tests were conducted from July 3, 1963 through January 29, 1965 under ARO Project No. VJ2604. The Program Element was 62410034, the Project 7778, and the Task 777806.

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**ABSTRACT**

The results from an experimental study of an expansion tube conducted at the von Karman Gas Dynamics Facility (VKF) are presented and discussed. The research was conducted in two facilities: (1) a 6.75-in.-diam Modified Expansion Tube (MET) which utilizes a partially steady and partially unsteady expansion process, and (2) a 4-in.-diam (constant diameter) High Density Shock Tube (HDST) operated in an expansion tube mode for a completely unsteady expansion of the shock-heated gas to the final test condition. Flow velocities from approximately 9000 to 16,000 ft/sec were studied. The theoretical performance of expansion tubes in terms of velocity is found to be nearly obtained; however, the steadiness of the resulting flow leaves much to be desired, and the definition of accurate flow conditions remains in serious doubt.



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## NOMENCLATURE

A	Cross-sectional area of tube
a	Acoustic speed
d	Inside diameter of tube
h	Enthalpy
$\ell_1, \ell_4, \ell_8$	Tube lengths (see Fig. 3)
$\ell_t$	Test gas slug length at time of rupture of secondary diaphragm
M	Mach number
$M_s$	Shock Mach number
P	Pressure
$P'_o$	Pitot pressure
$P_{HCW}$	Hemisphere-cylinder wall static pressure
r	Radial distance from tube centerline
T	Temperature
t	Time
U	Velocity
$U_s$	Shock velocity
x	Axial distance
$\gamma$	Ratio of specific heats
$\rho$	Gas density
$\tau$	Ideal test time from inviscid simple shock-tube theory

## SUBSCRIPTS

$1, 2, 2a, 3,$ etc.	Denotes various regions in shock tube flow (see Fig. 3)
$o$	Stagnation conditions
$\infty$	Free-stream conditions

## DUAL SUBSCRIPTS

Denotes ratio of quantities, example:

$$P_{ij} \equiv P_i/P_j$$

## SECTION I

### INTRODUCTION

The present need for advancement of ground test facilities for hypervelocity flow research is quite apparent from even a cursory survey of the attendant problems. A recent extensive survey paper by Cheng (Ref. 1) discusses many of these problems. The spectra of hypervelocity flow problems is indeed quite wide, and many different types of aerodynamic tools will be required to cover the ever-increasing domain of velocities and altitudes.

An aerodynamic test device utilizing an unsteady expansion to accelerate shock-heated gas was apparently first proposed by Resler and Bloxsom (Ref. 2) and was treated briefly by Hertzberg, et al. (Ref. 3). Trimpi (Ref. 4) was the first to make a detailed theoretical study of the expansion tube, i. e., a device in which the entire expansion from the shock-heated condition to the final test condition is performed unsteadily. The theoretical advantage of an unsteady expansion in hypersonic flow is evident from comparison of the steady and unsteady equations for isentropic expansions of the testing medium. For a steady expansion,

$$dU = -(dh/U)$$

whereas for an unsteady expansion,

$$dU = -(dh/a)$$

Thus, for hypersonic testing ( $U \gg a$ ,  $M \gg 1$ ) the unsteady expansion yields a velocity increment  $M$  times the steady expansion for a given incremental reduction in static enthalpy. It has been shown (Ref. 4) that for a given density level the test gas velocity obtainable with an expansion tube is approximately double that obtained by the shock tunnel for the same enthalpy level. Such a comparison is shown in Fig. 1.

Trimpi (Ref. 4) discussed both known and anticipated advantages and disadvantages of the expansion tube concept. One of the anticipated difficulties Trimpi mentioned is the fact that only an extremely small portion of the shock-heated gas is used for test purposes. Some insight into the problem can be gained from Fig. 2, which shows that for the expansion tube all of the shock-heated gas (air) used for test purposes

is in very close proximity to the secondary diaphragm at the time of its rupture.

A modification\* of the expansion tube concept is proposed herein to alleviate the test gas slug length problem, and experimental data from both modified and normal expansion tubes are presented and discussed.

## SECTION II DISCUSSION

The purpose of this investigation is to assess the value of an expansion tube as a hypervelocity aerodynamic test device. Flow uniformity is, of course, of major importance in aerodynamic testing, and because of the close proximity of the test gas to the rupturing secondary diaphragm, was of major concern in this investigation. To this end it was decided to investigate a modified version of the expansion tube designed to alleviate this problem.

The modification consisted of the addition of an area change (a supersonic nozzle) between the driven and the accelerating tubes (see Fig. 3). The shock-heated gas is expanded first by a steady expansion to the 2a conditions (Fig. 3) and then by an unsteady expansion to the test conditions (region 6).

The major advantage of such a modification is that there is a significant increase in the length to diameter ratio of the test slug,  $l_t/d_1$ , at diaphragm rupture and, hopefully, a corresponding increase in test gas uniformity. The major disadvantage is a decrease in performance due to the use of a partially steady expansion versus a completely unsteady expansion. This performance loss is shown as a function of area ratio in Fig. 4. (Note that the velocity parameter,  $U_\infty/\sqrt{2h_{02} - 2h_\infty}$  is a "coefficient of performance", i.e., it represents the gain in performance by the use of the unsteady expansion.) By using a nozzle with an area ratio of 10, the length parameter,  $l_t/d_1$ , is increased by over an order of magnitude while the "coefficient of performance" is decreased to about 1.5 for the cases considered herein, which represents a velocity loss of about twenty-five percent due to the steady expansion.

The idealized run time of a modified expansion tube with an abrupt area change is equal to that of a normal

---

\*Such a modification is discussed briefly by Hertzberg, et al. (Ref. 3).

expansion tube of the same length and test gas conditions. For a modified tube with a nozzle of finite length, the actual run time will be reduced by the nozzle start time and will depend upon the specific nozzle configuration.

During the course of this investigation, a question arose as to the effects of the nozzle itself on the test gas uniformity. An investigation was then undertaken in a 4-in.-diam buffered shock tube (the AEDC-VKF High Density Shock Tube - HDST). The tube was run as a normal expansion tube. Some experimental results are presented for this expansion tube as well as the modified version.

### SECTION III APPARATUS

#### 3.1 AEDC-VKF MODIFIED EXPANSION TUBE

The AEDC-VKF Modified Expansion Tube (MET) is shown in Fig. 5. The driver is 11 in. long with a 2.89-in. I.D. The driven section is 82 in. long and has a 1.58-in. diameter. A transition section (nozzle) between the driven and accelerating sections is 50 in. long. Its design will be discussed in the next paragraph. The accelerating section is 42-ft long and has a 6.75-in. diameter. An open-jet test section (15 in. in diameter by 2 ft long) is used and a 2-ft-diam by 12-ft-long dump tank completes the facility.

The area ratio,  $A_{81}$ , for this facility is 18.3, and the nozzle was designed by the method of Shapiro (Ref. 5). This is a sophisticated fairing procedure and does not rely on wave cancellation. Therefore, the design is not as sensitive to boundary-layer displacement thickness ( $\delta^*$ ) as the method of characteristics. Use of this method is based on the indication of Ref. 6 that it produces a shockless nozzle and the flow downstream is reasonably free of disturbances. For an initial shock Mach number  $M_{s1} = 6.9$  into 0.55-atm air, the nozzle entrance Mach number ( $M_2$ ) = 2.12 and exit Mach number ( $M_{2a}$ ) = 4.75. The boundary-layer displacement thickness was estimated to be very thin, and no correction was made for it. Real gas properties of Refs. 7 and 8 were used to calculate conditions throughout the entire flow process. The parameter  $\mu$  of Ref. 5 was chosen to be 8.25, and the nozzle exit angle is 0.08 deg. The resulting nozzle is a 7-deg half-angle cone with a diameter from 1.58 to 5.80 in. and a smooth contour from the latter dimension to 6.75 in. in diameter.

As was previously mentioned, the run time of a modified expansion tube is reduced by the nozzle start time. This start time is that time required for the head of the unsteady expansion to be swept through the nozzle. The start time for the MET nozzle is not accurately known. It is estimated that the start time for "standard" \* run conditions is nearly equal to the ideal run time. However, for most of the start time, the head of the unsteady expansion is in the contoured portion of the nozzle where the cross-sectional area is approximately equal to that of the accelerating tube. The effective nozzle start time is then somewhat less than actual start time, and probably leaves an appreciable run time, disregarding all other test-time loss mechanisms.

The MET operating regime is shown in Fig. 6 based on using room temperature ( $300^{\circ}\text{K}$ ) helium as the driver gas at a pressure of 1700 atm. The calculations are based upon ideal one-dimensional flow with no losses. Most runs were made at the "standard" condition, duplication altitude  $\approx 125,000$  ft and  $U_{\infty} \approx 14,000$  ft/sec. Theoretical gas properties in regions of interest are shown for the "standard" shot in Fig. 7.

In addition to the "standard" shot, the following special conditions were run:

1. reduced driver pressure,
2. increased accelerating tube pressure,
3. helium-air mixtures were used as the accelerating gas, and
4. by adding a small tube inside the accelerating tube (see Fig. 8) runs were made in the constant-area expansion tube mode.

### 3.2 AEDC-VKF HIGH DENSITY SHOCK TUBE

The AEDC-VKF High Density Shock Tube (HDST) shown in Fig. 9 was used for experiments of the unmodified concept. It is a 112-ft-long, constant, 4-in.-diam tube, 18 ft of which is the driver. The remaining 94 ft can be sectioned by diaphragms at various locations as desired. For these experiments the driven length is 64 ft, and the accelerating section is 18 ft long, with 12 ft remaining to allow for shock reflection.

The driver and driven tube charge conditions were held constant for all runs with room temperature ( $\approx 300^{\circ}\text{K}$ ) gases

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\*See Fig. 7 for "standard" shot conditions. Duplication altitude conditions based on U. S. Standard Atmosphere 1962 (Ref. 16).

used throughout:

$$P_4 = 680 \text{ atm} \text{ -- helium}$$

$$P_1 = 259 \text{ mm Hg} \text{ -- air}$$

The accelerating gas was air for all runs and the charge pressure ( $P_8$ ) was varied from 16  $\mu\text{Hg}$  to 18 mm Hg. Theoretical gas conditions in the regions of interest are presented in Fig. 10 for the case of  $P_8 = 16 \mu\text{Hg}$ .

### 3.3 MODELS

Several models (Fig. 11) were used in the MET phase of the tests. The hemisphere-cylinder and flat-faced cylinder were mounted on tube centerline and tested only at  $l_8 = 46$  ft (i.e., the test section). The pitot rake and the single pitot probe were tested at several longitudinal stations.

The pitot rake used in the HDST phase is shown in Fig. 12. The piezoelectric transducers were mounted in the recessed manner shown to protect the transducer from any large particles that might be in the flow. All tests in the HDST were made with the rake at  $l_8 = 18$  ft.

### 3.4 INSTRUMENTATION

Pressure and shock velocity measurements were made in these tests. Table I presents the instrumentation used and pertinent data. Transducer sensitivity, rise time, and filter configuration varied throughout the tests, and the values given in Table I are approximate.

For pitot pressure measurements, the transducer output caused by aerodynamic heating was found to be of the same order of magnitude as the pressure signal. It was determined that the transducer could be thermally protected by the application of a rubber mastic "gage kote" to the sensing surface. The application of this thermal shield did not change the transducer sensitivity or response time appreciably.

The monochrometer and photomultiplier setup consisted of a 2000 to 14,000 Å monochrometer set for a resolution of approximately 100 Å with a photomultiplier tube of unknown sensitivity placed at the exit slit. An approximate wavelength calibration was made by scanning the spectra of a neon indicator lamp. The entrance slit and associated lens were used to focus on an area approximately 0.1 in. square at the

nose of the hemisphere-cylinder. The output of the photo-multiplier tube was recorded on an oscilloscope.

## SECTION IV EXPERIMENTAL RESULTS

Early results in the modified expansion tube yielded pitot-pressure measurements which indicated the presence of strong timewise disturbances in the test gas. These disturbances, or "spikes", were found to be most pronounced on the tunnel centerline as can be seen in Fig. 13. The major effort of this investigation was directed toward the determination of the origin of these spikes. Runs were not made over a wide range of test gas conditions and most runs were made at the "standard" conditions listed in Fig. 7. Since the major point of interest was a timewise variation in test gas conditions, no great care was taken to insure the accuracy of the absolute level of the pressure measurements. There are some runs in which absolute value of pitot pressure and wall static pressure were measured to a reasonable accuracy and experimental results from these runs are presented and discussed in Section 4.2.

### 4.1 PITOT PRESSURE DISTURBANCES

The basic approach taken in the search for the origin of the spikes was:

1. hypothesize an agent which might cause the spike,
2. vary the apparent controlling parameter while holding others constant, and
3. look for changes in the nature of the spike greater than the normal run-to-run variation.

The various hypotheses and the parameteric variations accomplished to test the hypotheses are listed in Table II. The results are discussed below.

#### 4.2.1 Hypothesis I - Mechanically Induced Accelerations

Since the pressure transducers are very sensitive to acceleration normal to the sensing diaphragm, the possibility exists that the spikes are mechanically induced. This possibility was ruled out by making large changes in model and support system without effecting the character of the spikes.

#### 4.1.2 Hypothesis II – Instrumentation Difficulties

The possibility that the spikes were somehow generated by the pressure transducer and/or the associated electronic circuitry was considered. A pitot rake (Fig. 11c) was used to observe five pitot pressures simultaneously. These data (Fig. 13) show that the spikes are predominant on the tube centerline. A further check was made by completely interchanging the centerline and an off-axis instrument channel, and subsequent runs show the spikes to remain predominately on the tube centerline. From these checks and the tests discussed in Section 4.1.1, it was concluded that the spikes were not mechanical or electronic in nature but rather indicated flow disturbances.

#### 4.1.3 Hypothesis III – Flow Instability on Model

The initial indications of spikes were obtained from the flat-faced cylindrical model (Fig. 11b) (typical traces shown in Fig. 14), thus the possibility that the spikes could be induced by some model-flow instability was considered. Smaller diameter, flat-faced probes (e.g., the pitot rake, Fig. 11c) and hemisphere-cylinder (Fig. 11a) models were tested, and typical traces from these tests are shown in Figs. 13 and 15, respectively. The radial location of the models was found, for example, to be far more critical with regard to the character of the spikes than the model configuration.

#### 4.1.4 Hypothesis IV – Oblique Shock from Wall

The fourth hypothesized agent was an oblique shock wave which arrives at the test section approximately on the tunnel centerline. Slight timewise flow variations would lead to movement of the shock across the centerline pitot probe which would cause variations in the centerline pitot pressure, but would not greatly affect the pitot pressure off centerline. A longitudinal pitot survey using either the pitot rake (typical traces shown in Fig. 16) or a single centerline pitot probe (typical traces shown in Fig. 17) indicated that the pitot spikes were present on centerline for all longitudinal stations checked, thus apparently eliminating the oblique shock hypothesis.

#### 4.1.5 Hypothesis V – Accelerating-Tube Viscous Effects

The fifth hypothesis is that the spikes are caused by viscous effects in the accelerating tube. A major constituent of the boundary layer in the accelerating tube is the shock-heated accelerating gas which is normally air. Several runs were made with helium-air mixture as the accelerating gas,

thus changing the boundary-layer constituents, with no noticeable change in the nature of the pitot spikes (typical traces shown in Fig. 18). The small, but finite, normal leakage of room air into the accelerating tube precluded the use of highly pure helium. The helium concentration was varied from sixty-five to ninety percent (by volume).

#### 4.1.6 Hypothesis VI—Secondary Diaphragm Rupture Effects

The secondary diaphragm is a natural suspect for producing the pitot spikes because of the proximity of the test gas to the diaphragm at the time of rupture (for the standard shot  $l_t \approx 0.84$  in.). To check this possibility, diaphragm thickness was varied from 0.00025 to 0.008 in., and several different materials were used. Figure 19 presents what is considered to be the spread of the data using a 3/4-mil polyester secondary diaphragm. All other diaphragms tested with the exception of the aluminum foil secondary diaphragm yielded pitot traces which appeared to fall within this scatter.

Figure 20 shows the results for the aluminum foil secondary diaphragm. The three traces presented are representative of run-to-run variations. Note that the time scale of the traces of Figs. 19 and 20 are the same and that there is a change in the character of the spikes and no change of the static pressure trace.

#### 4.1.7 Hypothesis VII—Flow Contamination by Secondary Diaphragm

For high Mach number flow,

$$P'_o \approx K \rho U^2 \quad (1)$$

Pitot spikes could then be caused by steep gradients in density. Gaseous contamination from the secondary diaphragm is one possible source of dense gas. A monochrometer at the test section was used to detect this contamination when an aluminum foil diaphragm was installed. The monochrometer was set to pass narrow bandwidth radiation about a strong aluminum line (3090 Å). Although another aluminum line is stronger, it is near other predominate spectra. The data obtained (Fig. 21) indicate that this contamination arrives during the useful flow but shows no correlation with the pitot disturbances which appear later in the flow. The run with a polyester secondary diaphragm (Fig. 21) served as a "tare" run (i.e., aluminum contamination was not detected). It should be noted that this technique may be insensitive to relatively cool particle contamination.

#### 4.1.8 Hypothesis VIII – Area Change Effect

The AEDC-VKF modified expansion tube makes use of a steady expansion (nozzle) prior to the unsteady expansion. It is questionable that this nozzle actually has time to start during the short run time. In addition, there is a good possibility that some weak shock waves are formed in the turning process although the nozzle is supposedly contoured to eliminate shock formation. It is not obvious how either of these difficulties would result in pitot spikes; however, it is plausible. As a check, a 1.6-in.-diam tube was inserted inside the accelerating tube (Fig. 8), thus eliminating the nozzle. An attempt was made to position a single pitot probe on tube centerline. However, it was necessary to position the pitot probe externally, and it may have been slightly off centerline. The data from this probe (Fig. 22) show no spikes, but the character of the trace cannot be explained. The possibility exists that the tube, which was not exceedingly smooth, was completely filled with boundary layer at the test station.

The results from the constant-area tube were promising, at least in that they showed no pitot spikes, and further study seemed advisable. In order to relax problems inherent with the small diameter tube, the experiment was continued in the AEDC-VKF Pilot High Density Shock Tube (HDST) operated as a constant-area expansion tube. Early runs, while producing little usable aerodynamic data, clearly demonstrated, through several mechanical failures, the high drag loads present during the passage of the unsteady expansion fan.

A second operational problem demonstrated by the constant-area experiment was the hazardous location of transducers with respect to material lost from the rupturing primary diaphragm. For the original runs in the 4-in. expansion tube, the pitot-rake probes were instrumented with flush-mounted transducers as was the case in the MET. After losing several transducers from damage caused by diaphragm particles, it was decided to give the transducers some protection by recessing them into the probe. The specific configuration used along with a comparison of pressure measurement using each mounting technique is shown in Fig. 23. Although the pressure traces are not identical, the recessed gage seems adequate both in terms of response and acoustical ringing of the cavity.

The constant-area experiment was carried out holding the driver and driven tube conditions constant and varying the accelerating tube charge pressure and thus the length of the test gas slug,  $l_t$ . (For  $P_8 = 16 \mu\text{Hg}$ ,  $l_t \approx 0.035 \text{ in.}$ ; for  $P_8 = 18 \text{ mm Hg}$ ,  $l_t \approx 7.7 \text{ in.}$ )

Typical run traces for runs with low  $P_8$  (and therefore relatively short initial test slug length) are shown in Figs. 24 and 25. Once again, there are large disturbances on the pitot pressure traces. The shape of these disturbances is somewhat different from those observed in MET; however, their relative magnitudes are approximately the same.

Typical run traces for runs with high  $P_8$  (and therefore relatively long test slug length) are shown in Fig. 26. Here, the disturbances occur at a much higher frequency and are of somewhat reduced relative amplitude. Whether the disturbances on these traces are the same phenomena as those at the lower  $P_8$  is a matter of conjecture; however, from continuity considerations it is expected that frequency of the disturbances should decrease as the gas is further expanded. In addition, if the disturbances are density gradients, their amplitude relative to the mean pitot pressure is expected to increase as the ratio of dynamic to static pressure increases. It is possible then, that the disturbances seen on both low and high pressure runs may result from the same basic phenomena but appear different in frequency and amplitude because of the amount of expansion permitted.

It is interesting to compare the pitot pressure trace before and after arrival of the interface. This comparison is shown in Fig. 26 for a case where the pitot pressures before and after the interface are not vastly different. From these traces it is apparent that the uniformity of the shock-heated gas (region 7) is superior to that of the expanded gas (region 6).

Assuming that the disturbances are in some way induced by the secondary diaphragm, it is expected that they should diminish in time since the gas arriving at the test station later in time was further from the secondary diaphragm at the time of rupture. The traces, in fact, show little indication of disturbance attenuation in the available test time. Two diametrically opposed possibilities are apparent:

1. The disturbances are not caused by the secondary diaphragm, or
2. The effects of the secondary diaphragm are so extensive that the entire test slug length was affected to approximately the same degree.

Since the disturbances arrive at the same time as the interface, the first possibility seems somewhat remote.

#### 4.1.9 Summary

Of the many hypotheses tested only two showed any effect on the spikes:

1. Deletion of the area change affects the shape of the disturbances, but disturbances of about the same relative magnitude as that of the MET spikes are present even without an area change.
2. Changes in secondary diaphragm material appreciably changed both the shape and the time of arrival of the spikes but had little effect on their magnitude.

### 4.2 PERFORMANCE DATA

Although the uniformity of the test gas leaves much to be desired, it is of interest to compare approximate mean levels of the measured data with theoretical predictions.

#### 4.2.1 Velocity

No direct measurement of flow velocity was attempted; however, it can be shown from viscous considerations (Refs. 9, 10 and 11) that the interface velocity (and therefore the test gas velocity at the interface) is approximately equal to the accelerating tube shock velocity,  $U_{Sg}$ . This shock velocity was found to be slightly below theory at the test section (Figs. 27 and 28), which implies that the flow velocity is in reasonable agreement with theory. The theory is based upon measured values of  $M_{S1}$ ,  $P_1$ ,  $P_g$ , and one-dimensional inviscid flow using the thermodynamic properties of Ref. 12. The runs represented by the scatter band contain data from all runs in which reasonably reliable absolute pressure measurements were made.

Driven tube shock velocity,  $U_{S1}$ , is compared with theory in Figs. 29 and 30. The theory was based upon one-dimensional inviscid flow with no losses. The driver gas, helium, was considered to be perfect, and the driven gas, air, was considered real, using the thermodynamic properties of Ref. 12. The initial shock strength was found to be slightly above theory and for the high  $P_{41}$  case in MET, initially increases with time. Both of these phenomena were observed by White (Ref. 13) who attempts to explain them by a "formation from compression" model.

## 4.2.2 Pitot Pressure

Pitot pressure was measured on all the models shown in Fig. 11. No significant model-to-model variation was found in either level or uniformity of the pitot pressure. To attempt to determine the level of pitot pressure for these runs is perhaps a bit courageous, but it was felt that even an approximate level might be a worthwhile piece of information at this point in expansion tube development.

The MET traces were read at a time,  $t_1$ , (Fig. 13) soon after the arrival of the interface but purposely chosen to avoid spikes. For the MET runs with the pitot rake, a second time,  $t_2$ , (Fig. 13) was chosen after the rapid decrease in pitot pressure on the two outer probes (apparent arrival of the boundary layer). Once again, the time,  $t_2$ , was chosen to avoid spikes. The HDST traces were read at a time  $t_1$  (Fig. 24) immediately after the arrival of the interface, and here the pressure level was determined by fairing through the disturbances.

Measured centerline pitot pressures are compared with theory in Fig. 31. The theoretical calculations are based upon:

1. Measured  $U_{S1}$  and  $P_1$  ( $T_1$  assumed to be room temperature)
2. Normal shock crossings using the thermodynamic properties of Refs. 12 and 13 to determine conditions in region 2.
3. Isentropic expansion of the gas in region 2 to  $U_6 = U_{S8}(\text{measured})$  using the properties of Refs. 12 and 13.
4. A steady isentropic expansion (for MET) calculated from the geometric area ratio, i.e., zero boundary-layer displacement thickness.

The estimated overall accuracy in measured  $P_0$  is  $\pm 12\%$ . The measured pitot pressure is in reasonable agreement with theory for the low velocity runs, but is considerably below theory for the higher velocity runs. It should be remembered that the higher velocity runs have a stronger unsteady expansion fan and a lower pitot pressure.

Observed pitot pressure profiles in MET are shown in Fig. 32. As previously stated, the two times,  $t_1$  and  $t_2$ , are before and after the apparent arrival of the boundary layer

at the two outer pitot probes. Pitot profiles from the HDST are shown in Fig. 33. A rapid decrease in pitot pressure on the outer pitot probes corresponding to that observed in MET was not found. Theory in both cases was calculated as previously described.

#### 4.2.3 Wall Static Pressure

Typical oscilloscope traces of the wall static pressure measurements are shown in Fig. 34. The "dip" in static pressure from the MET runs is typical and, like the spikes, is yet to be explained. The results of the static pressure measurements are shown in Fig. 35. The MET traces were read at the same point in time,  $t_1$ , as on the pitot trace. The estimated accuracy is  $\pm 17\%$ . Here again, the measured pressure is in fair agreement with the theory for low velocity runs but is considerably low for the higher velocities. The theoretical free-stream static pressure was calculated using the same assumptions listed for the calculations of  $P_0^{\text{theory}}$ .

Reliable pitot pressure and wall static pressure were obtained concurrently in only six runs - three in MET at low pressures and three in HDST at high pressure. The measurements are compared to theory in Figs. 36 and 37. The theory was obtained as described previously except that the gas in region 2 is expanded to a given  $P_6$ , whereas previously it was expanded to a given  $U_6$  ( $= U_{S8}$ ). The results agree reasonably well with theory for both the high pressure and low pressure runs. This could be anticipated from the previous comparisons since both pitot and wall static pressure were in agreement with theory at high pressure and both low at low pressure. It should be noted here, that the theoretical velocities,  $U_6$ , obtained by expanding to  $P_6^{\text{(measured)}}$  are approximately 7 percent higher than the experimentally observed  $U_{S8}$  values for MET (Fig. 36). For the HDST (Fig. 37) the only data presented are for higher pressures, and here the theoretical velocity,  $U_6$ , is slightly less than  $U_{S8}^{\text{(measured)}}$ .

#### 4.2.4 Shock-Interface Separation

The separation time between the shock and the apparent interface can be determined from the pitot pressure trace. This time is compared to the theory of Mirels (Refs. 10 and 11) as a function of  $P_8$  in Fig. 38. For low  $P_8$  the spread of the data becomes large and the agreement with theory becomes poor.

Shock and interface curvature was obtained by determining their time of arrival at each probe of the pitot rake

in MET. The time scale was expanded for several runs in order to increase the experimental accuracy. Results of these runs are presented in Fig. 39. The rise time of the pressure transducer precluded very accurate measurements of shock curvature; however, the results are in reasonable agreement with those of Ref. 14. The curvature of the interface was so severe that the transducer rise time was comparatively insignificant. Also the large scatter in  $t_7$  (Fig. 38) is seen here as a run-to-run variation in the separation distance.

#### SECTION V CONCLUSIONS

Based on the results of this experimental study of an expansion tube, the following conclusions are made:

1. Expansion tube performance in terms of shock velocity and, therefore presumably flow velocity, is in reasonable agreement with theoretical predictions.
2. Pitot pressure measurements on centerline indicate flow disturbances of sufficient magnitude to preclude meaningful aerodynamic testing during these disturbances. No firm conclusions can be drawn as to the source of these disturbances; however, the present results point to the secondary diaphragm as the possible source of these disturbances.
3. A brief test time can be chosen such that both wall static and pitot pressures are fairly constant in time; however, during this time both pressures are somewhat lower than expected based upon measured shock velocities, and thus the definition of accurate test conditions during even this time remains in serious doubt.

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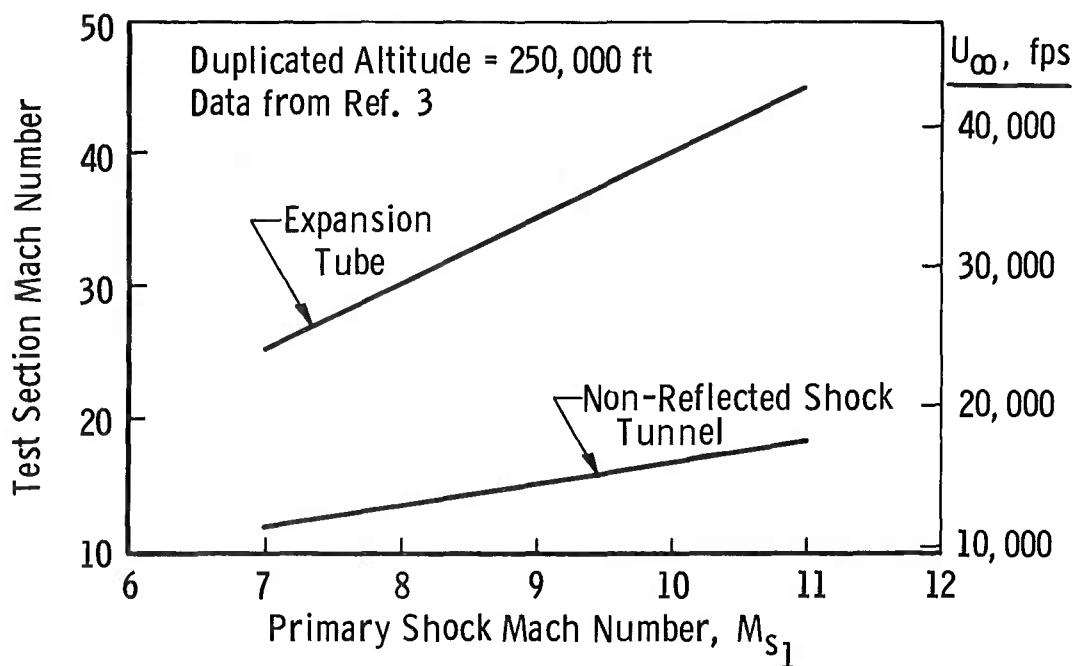


Fig. 1 Comparison of Expansion Tube and Shock Tunnel

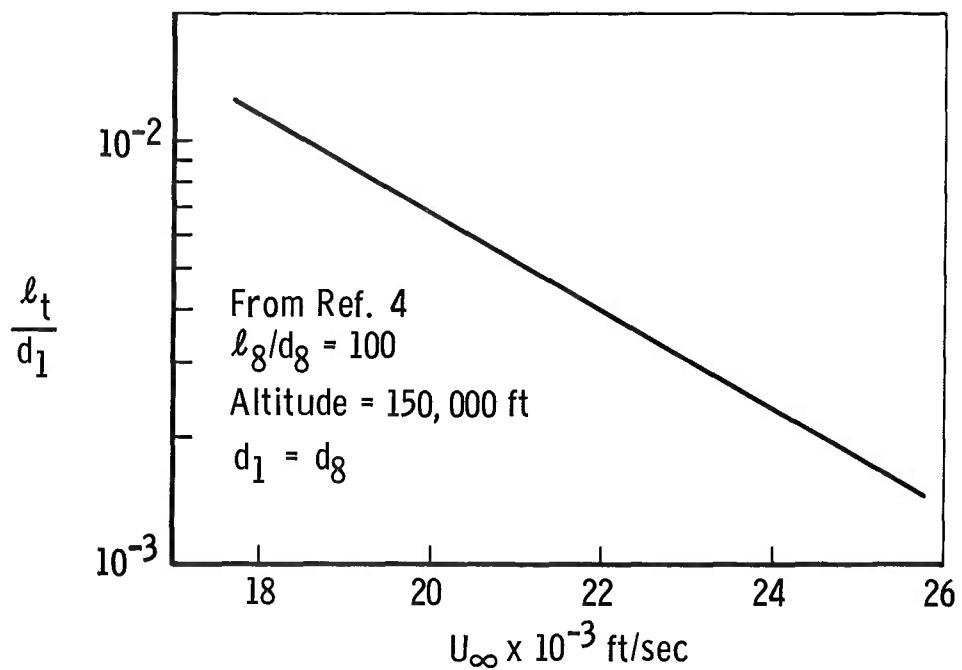


Fig. 2 Proximity of Test Gas to Secondary Diaphragm - Expansion Tube

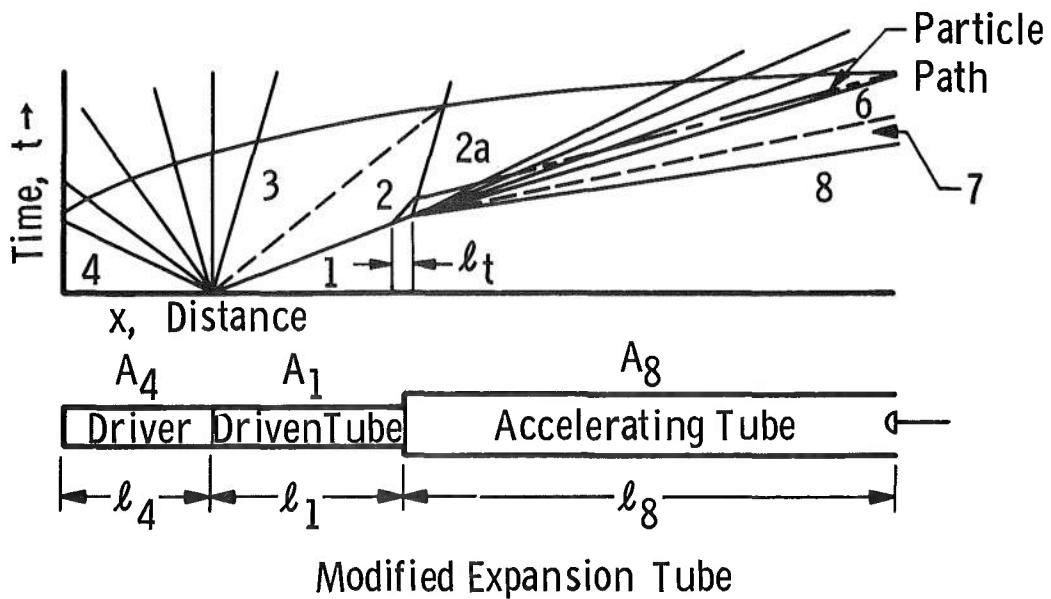
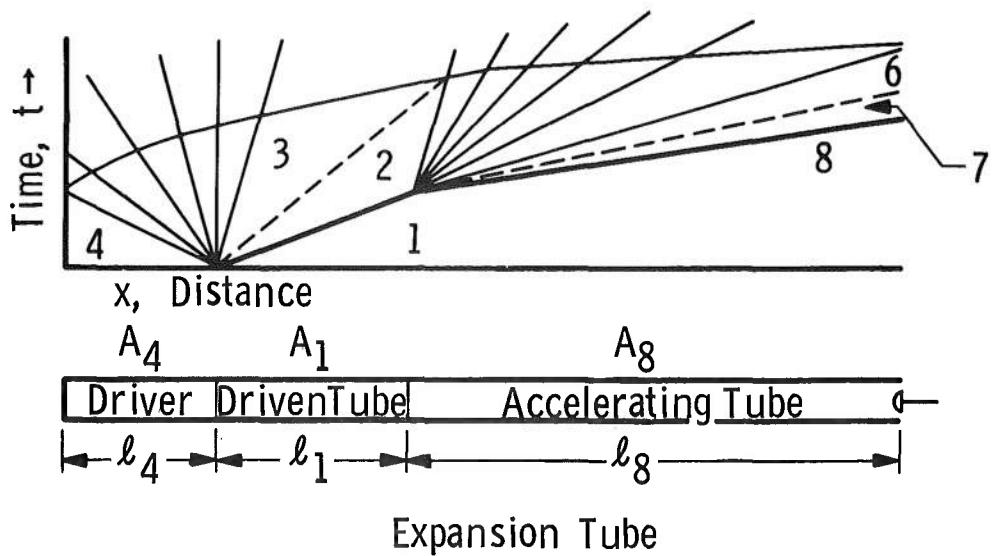


Fig. 3 Wave Diagram - Schematic

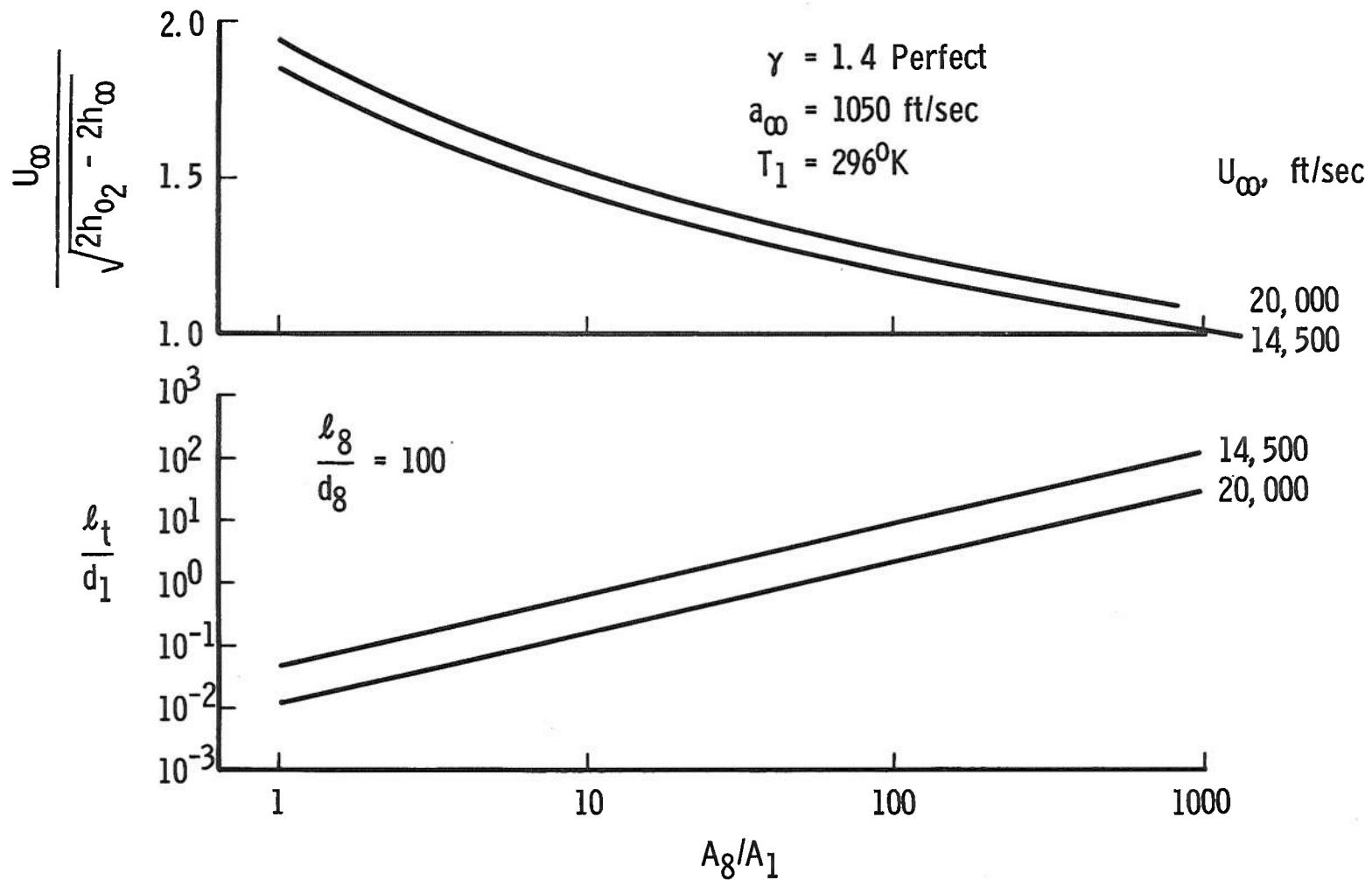


Fig. 4 Variation of Performance and Test Slug Length with Area Ratio

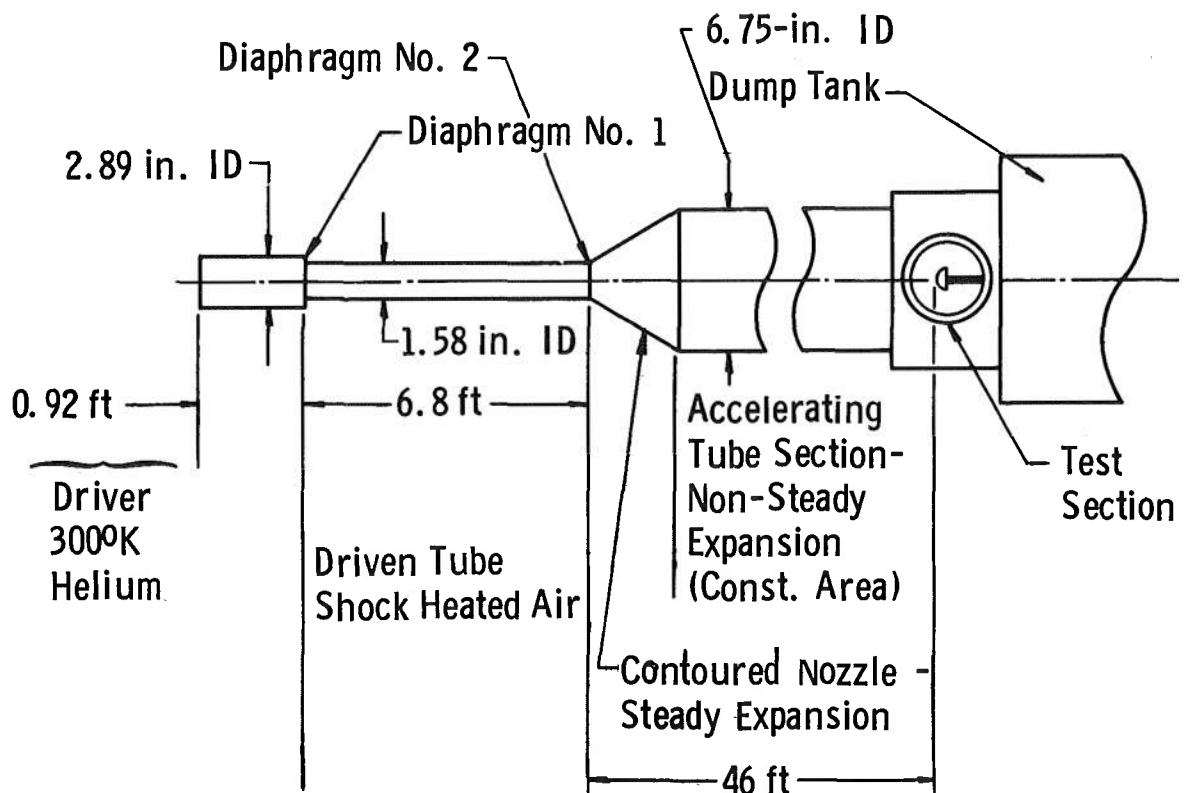
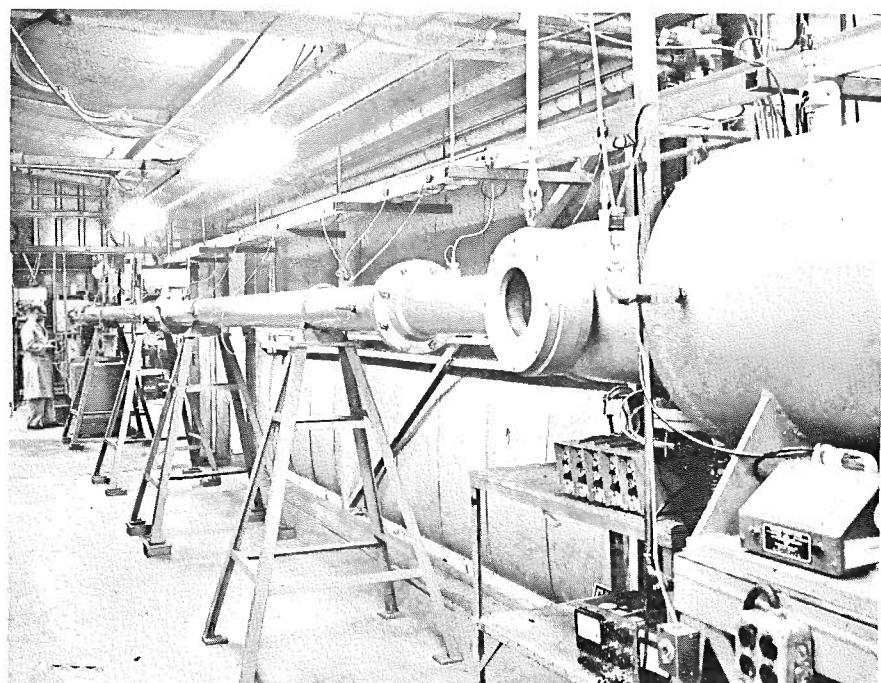


Fig. 5 AEDC-VKF Modified Expansion Tube

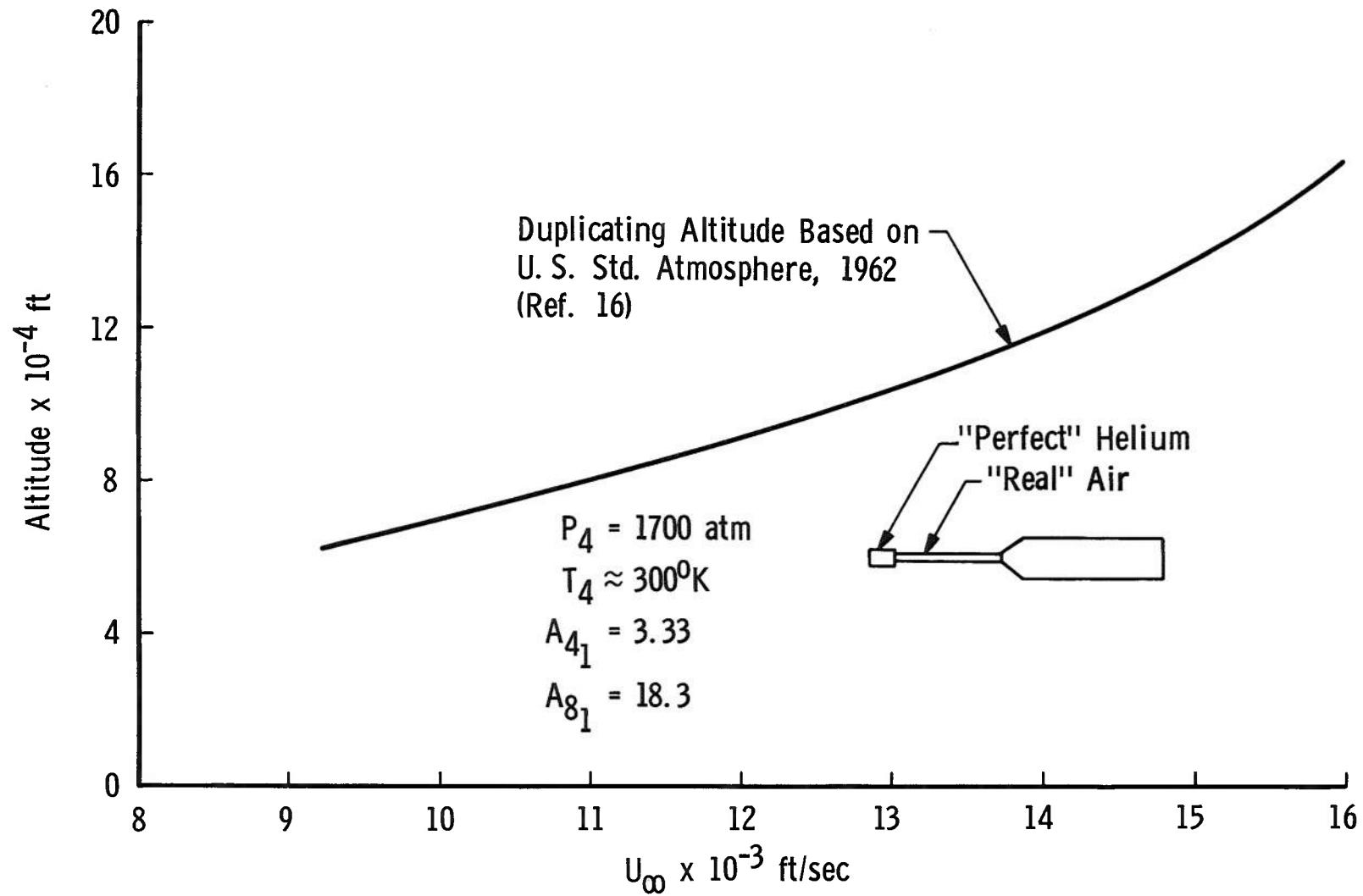


Fig. 6 Altitude-Velocity Regime, Modified Expansion Tube

	4	2	1	2a	6*	7	8
U, fps	0	6570	0	9300	14,100	14,100	0
P, atm	1700	28.7	0.55	0.44	$3.61 \times 10^{-3}$	$3.61 \times 10^{-3}$	$14.5 \times 10^{-6}$
a, fps	3310	3070	1135	1960	1031	4350	1135
T, $^{\circ}$ K	290	2400	296	935	246	4350	296
M	0	2.12	0	4.75	13.7	3.25	0

\* Duplicated Altitude  $\approx$  125,000 ft

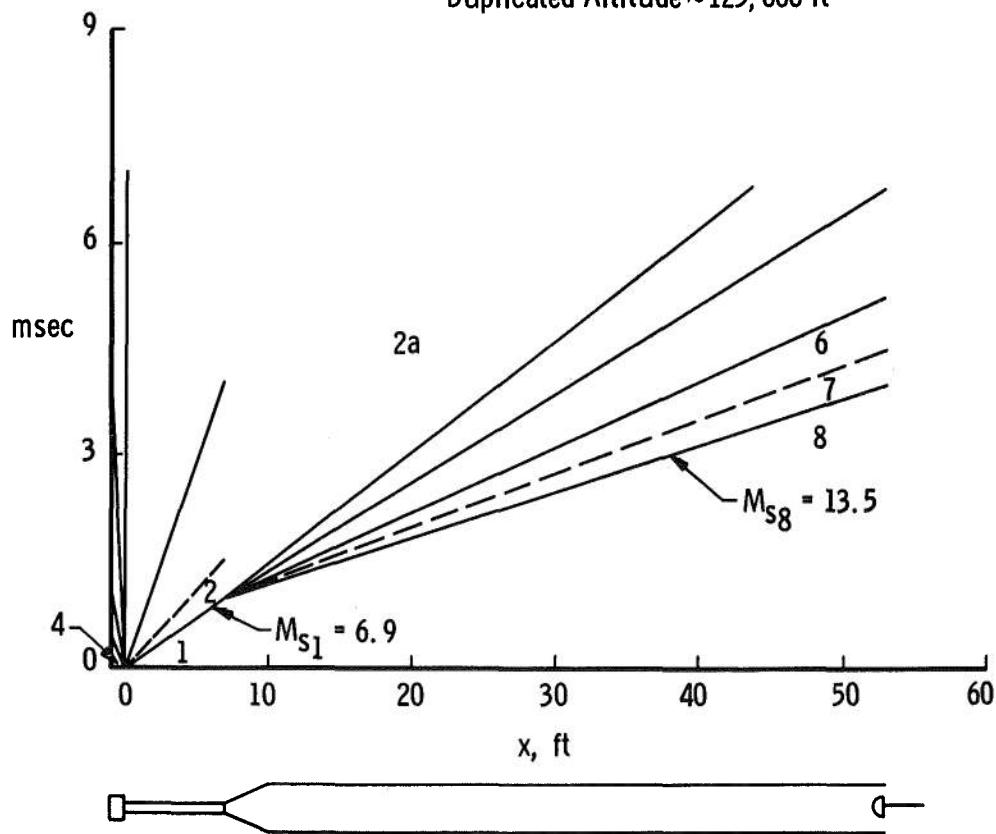


Fig. 7 Modified Expansion Tube - Flow Properties, "Standard Conditions"

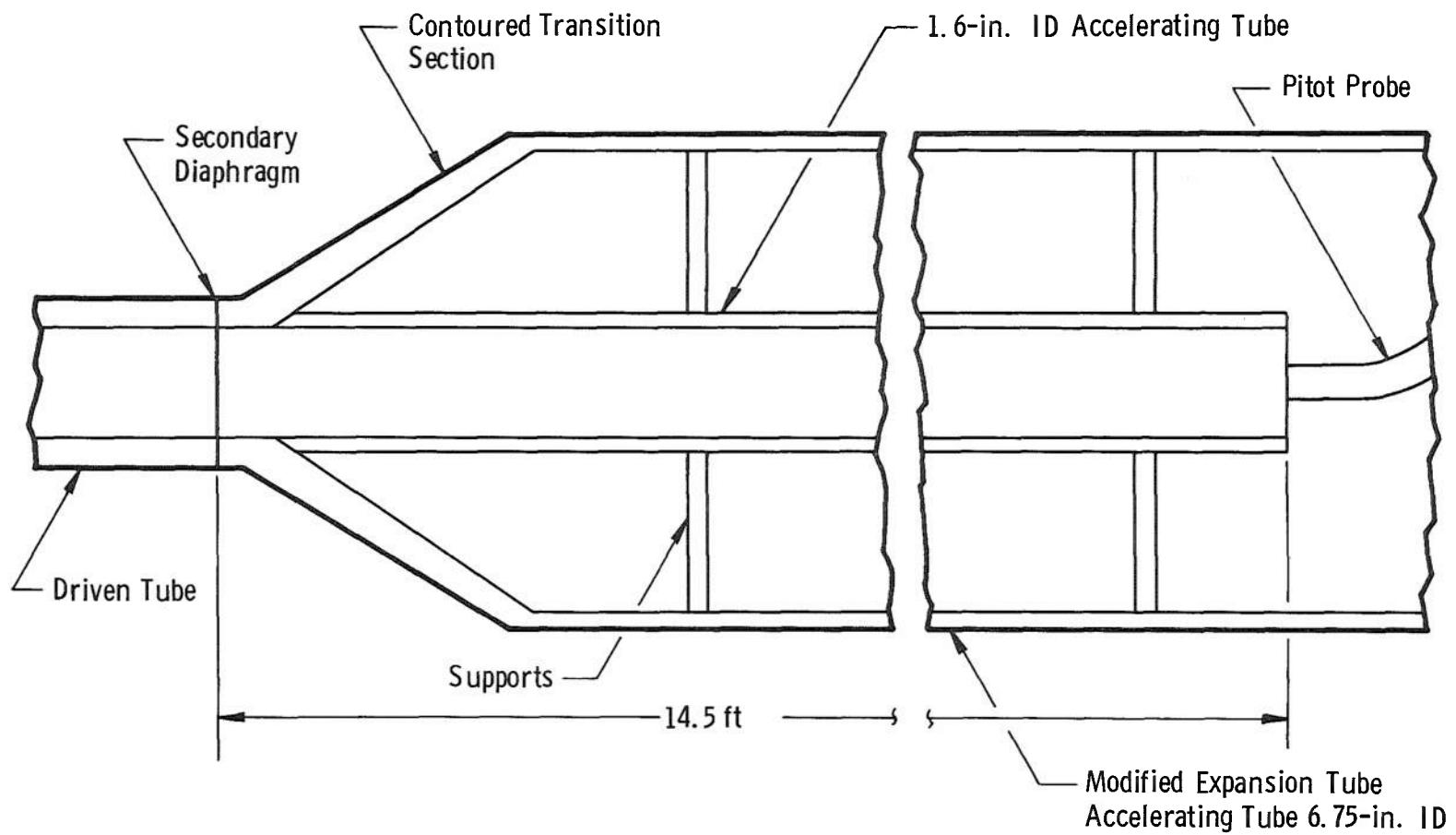


Fig. 8 Constant Area Tube Installation – Schematic

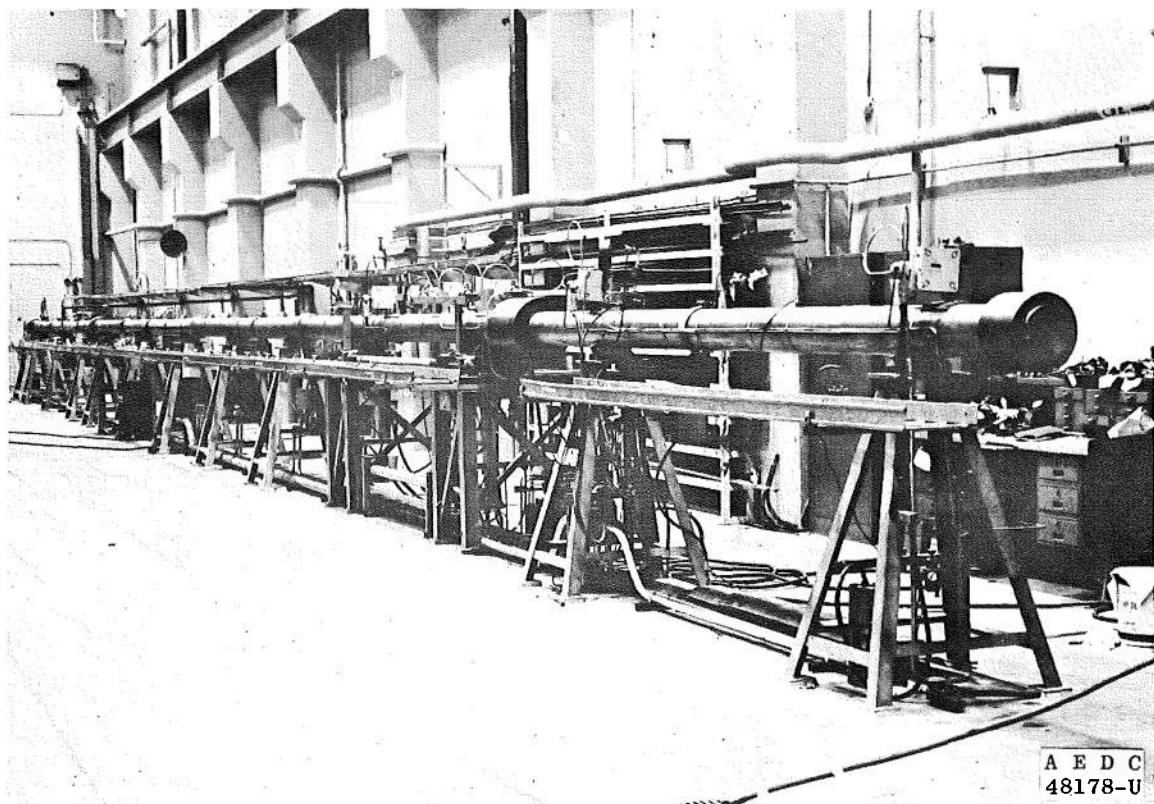
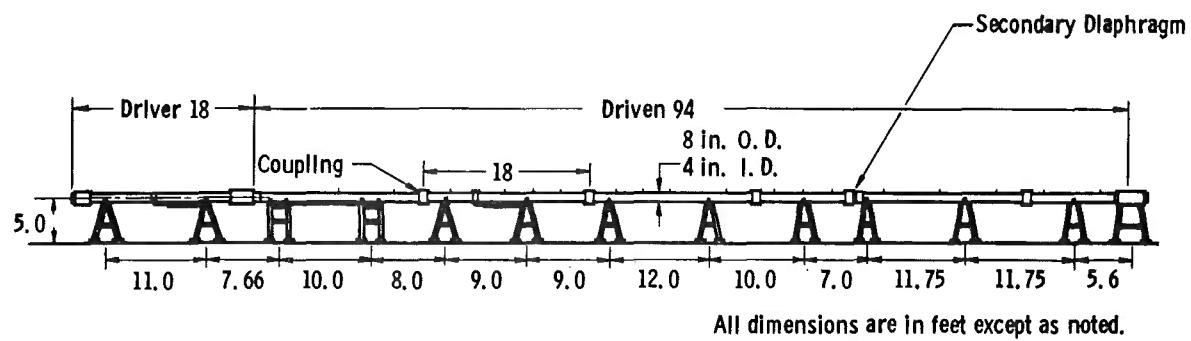


Fig. 9 AEDC-VKF High Density Shock Tube

	4	3	2	1	6	7	8
U, fps	0	5200	5200	0	16,500	16,500	0
P, atm	680	12.2	12.2	0.33	0.00673	0.00673	0.000021
a, fps	3350	1510	2830	1130	962	4800	1130
T, $^{\circ}$ K	296	59	1950	296	225	4920	296
M	0	3.44	1.84	0	17.20	3.44	0

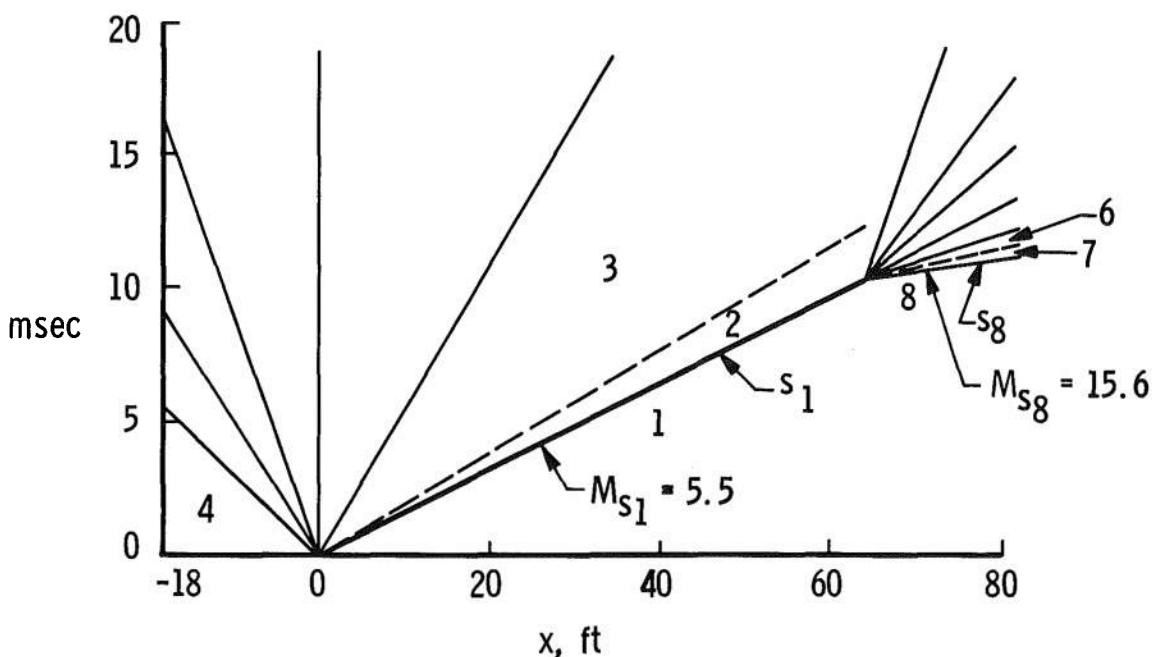


Fig. 10 High Density Shock Tube - Flow Properties ( $P_8 = 16 \mu\text{Hg}$ )

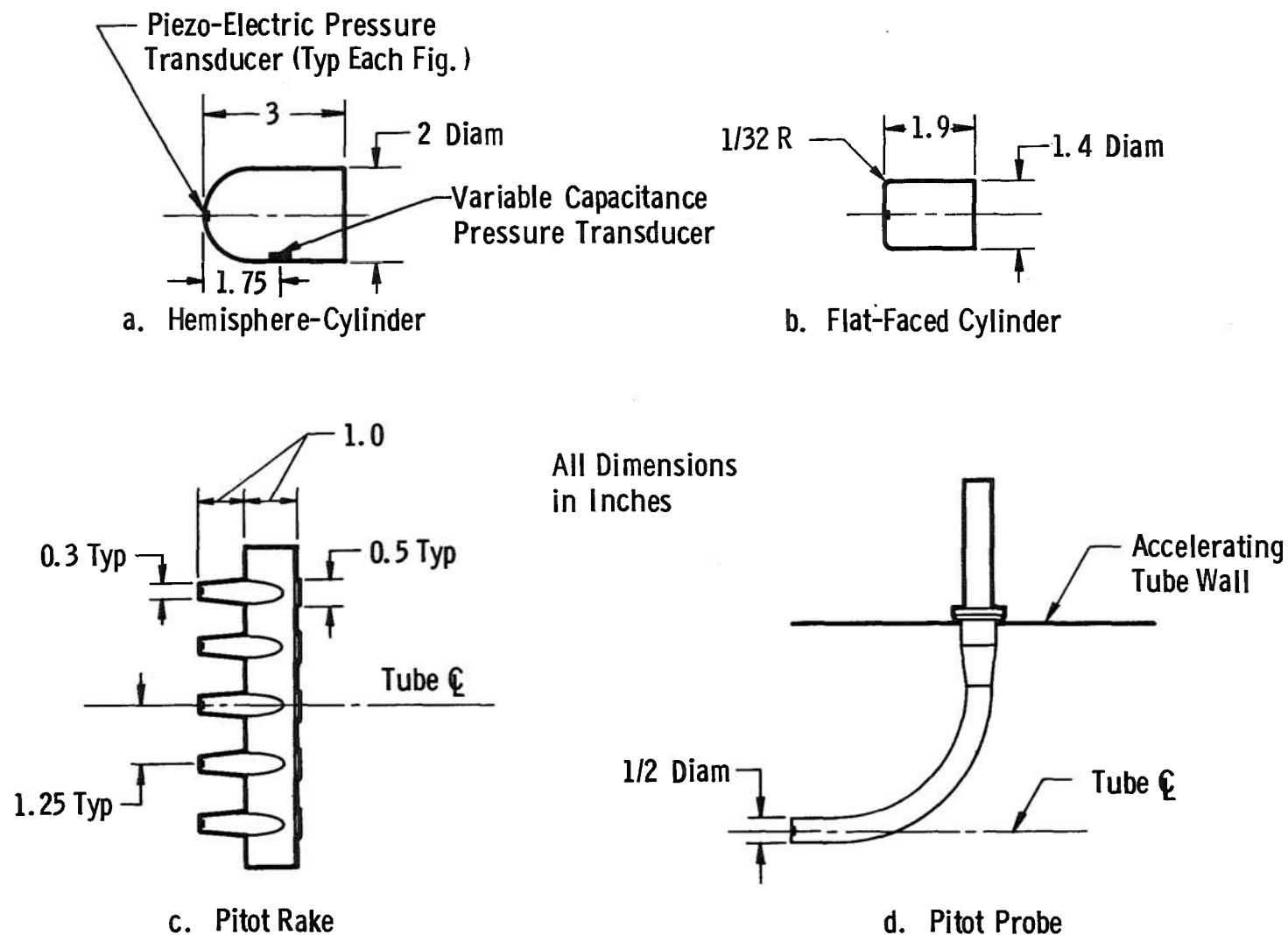
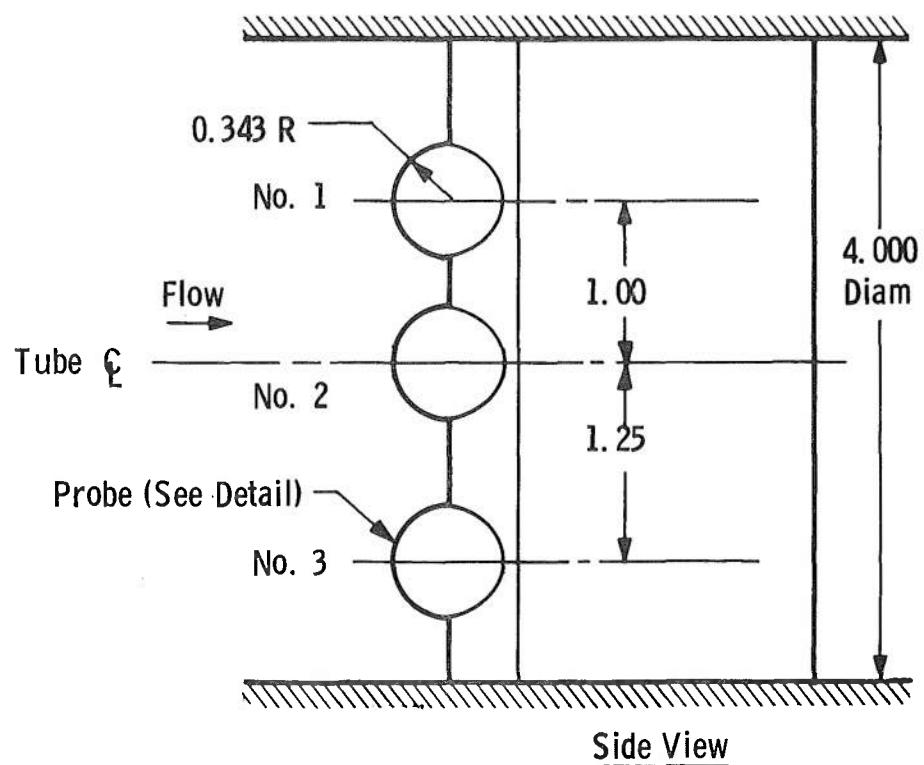
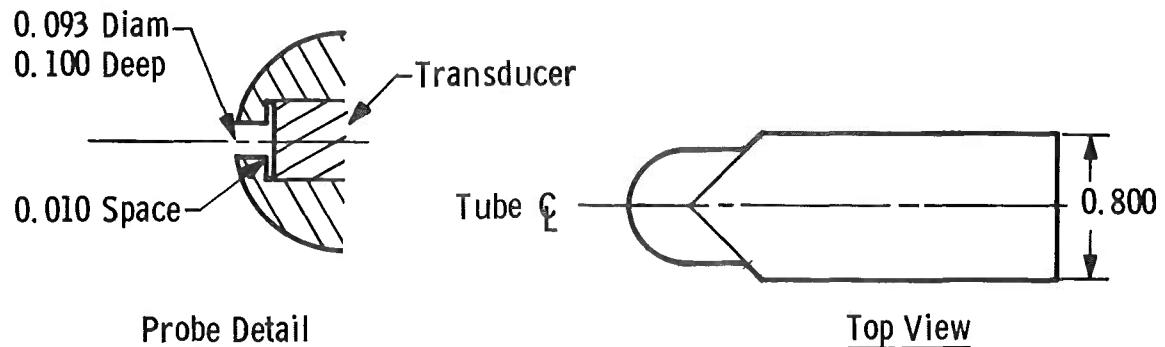


Fig. 11 Models - Modified Expansion Tube



Note: All Dimensions in Inches

Fig. 12 Pitot Rake - High Density Shock Tube

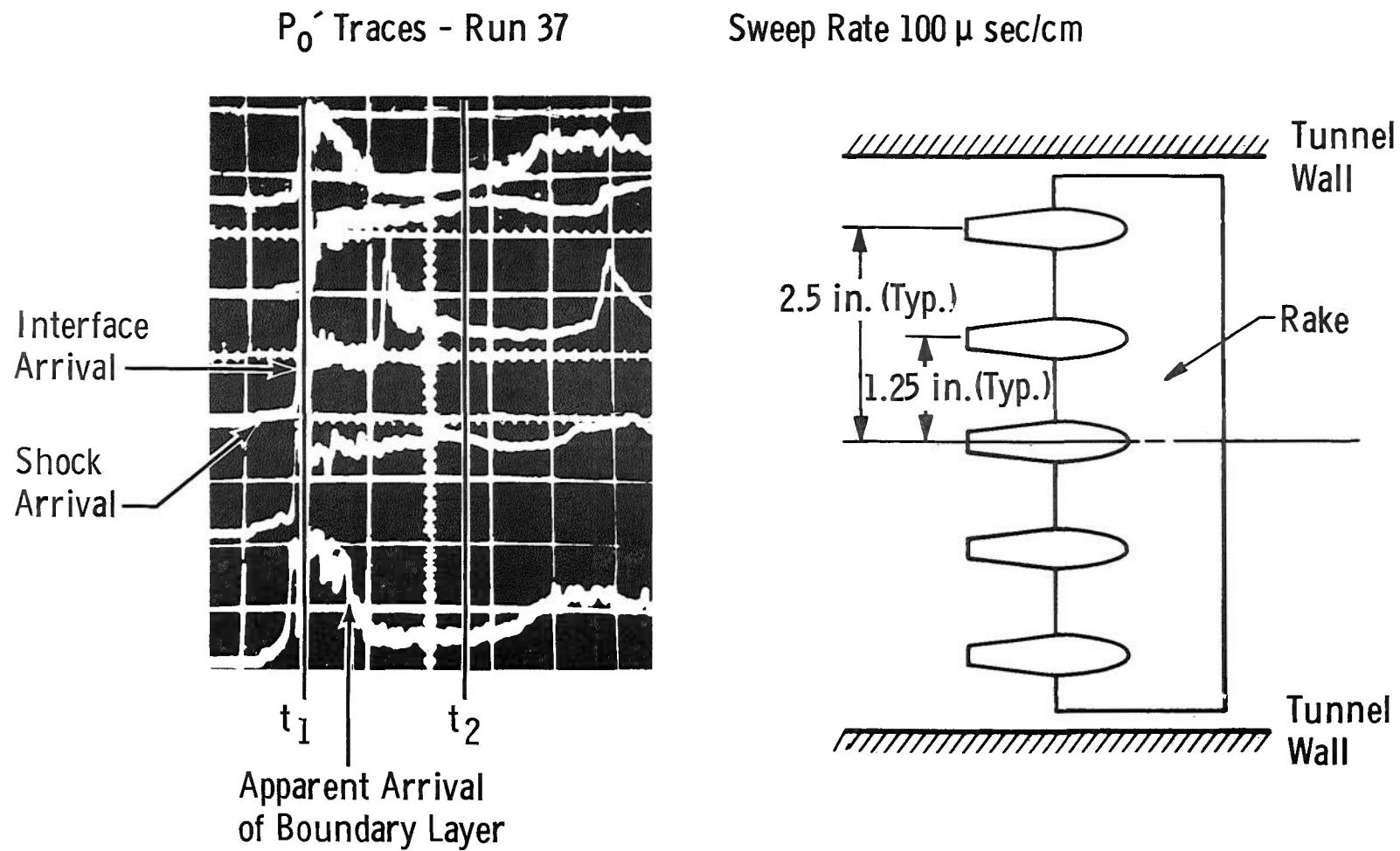
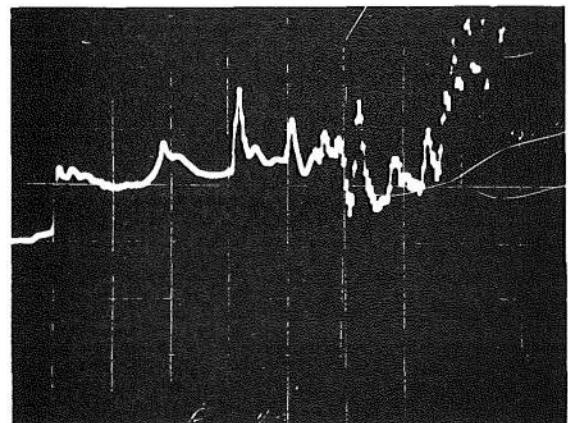


Fig. 13 Sketch of Rake and Sample Pitot Pressure - 6.75-in. Modified Expansion Tube

Run 21



$P_4$  - 462 to 490 atm (Helium)

$P_1$  - 304 mm Hg (Air)

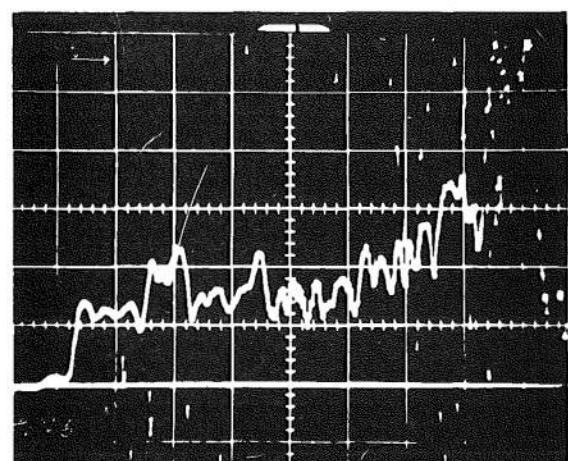
$P_8$  - 18  $\mu$  Hg (Air)

$M_{S8}$  - 10.8 to 11.4

$l_8$  - 46 ft

Sweep Rate - 200  $\mu$  sec/cm

Run 23



Run 25

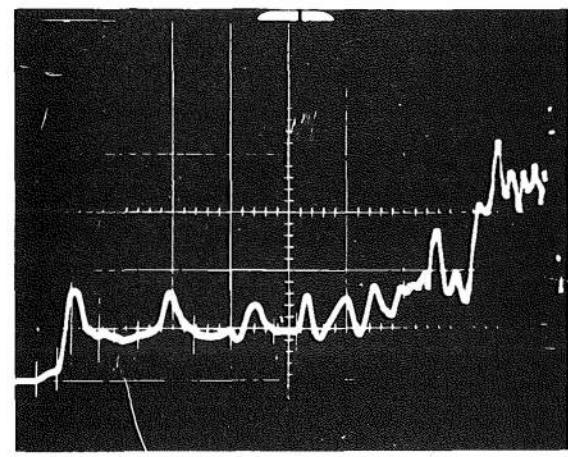


Fig. 14 Typical Pitot Traces for a Flat Face Cylinder Model

$P_4$  - 1190 to 1260 atm (Helium)

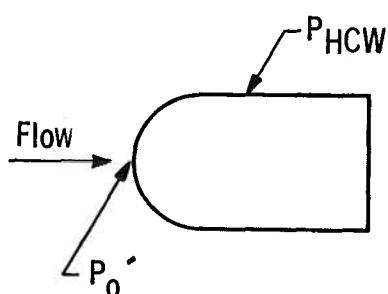
$P_1$  - 455 mm Hg (Air)

$P_8$  - 17  $\mu$  Hg (Air)

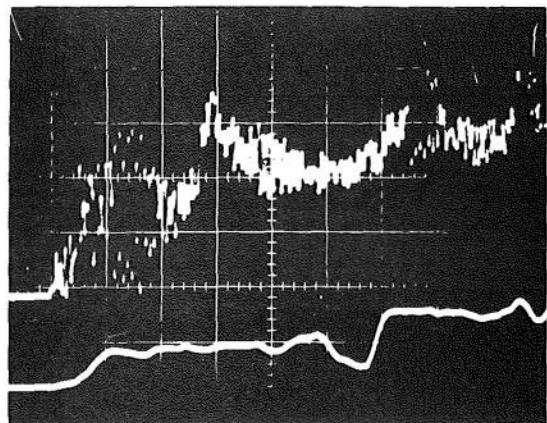
$l_8$  - 46 ft

$M_{S8}$  - 13.7 to 13.3

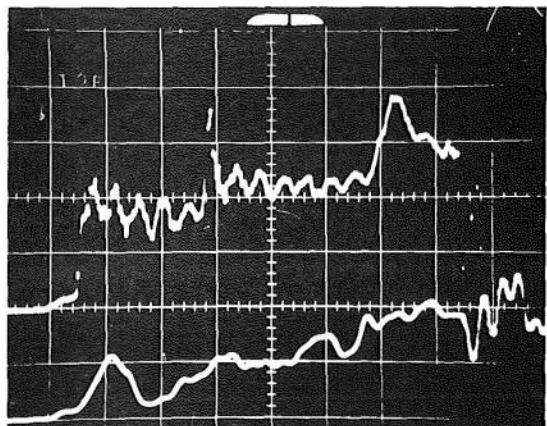
Sweep Rate 100  $\mu$  sec/cm



Run 85



Run 87



Run 90

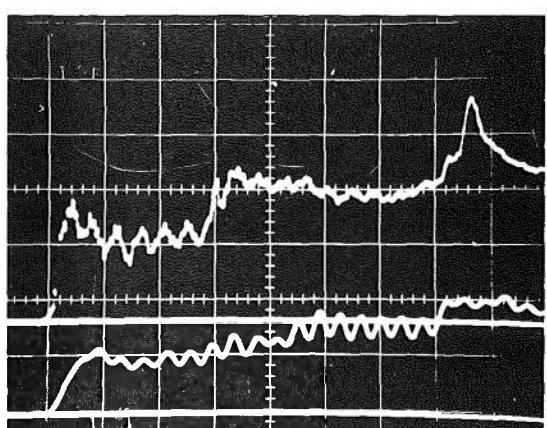
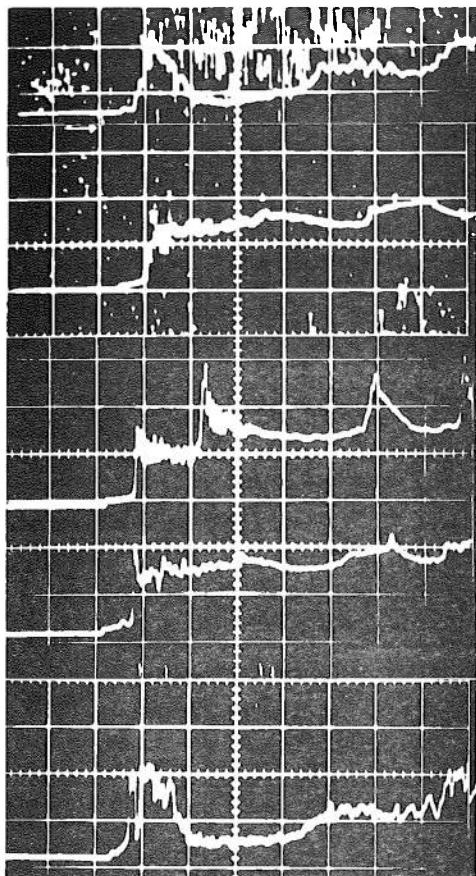


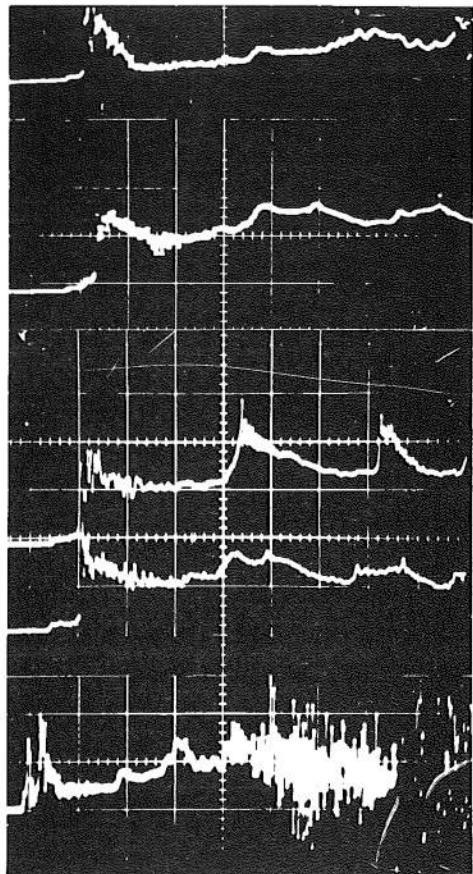
Fig. 15 Typical Pitot Traces for a Hemisphere-Cylinder Model



Run 37  
 $l_8 = 38.5$  ft

$P_4$  - 455 atm  
 $P_4$  - 304 mm Hg (Air)  
 $P_8$  - 18  $\mu$  Hg (Air)  
 $M_{S8}$  10.9 to 11.8  
 Sweep Rate 100  $\mu$  sec/cm  
 Note: Sweep Rate Run 41  $P_0'$  ( $r = 2.5$  in.) 200  $\mu$  sec/cm

$P_0'$   
 $r = 2.5$  in.  
 $P_0'$   
 $r = 1.25$  in.  
 $P_0'$   
 $r = \frac{1}{2}$   
 $P_0'$   
 $r = 1.25$  in.  
 $P_0'$   
 $r = 2.5$  in.



Run 41  
 $l_8 = 42$  ft

Fig. 16 Pitot Rake Traces – Two Different Accelerating Tube Lengths

$P_4$  - 440 to 483 atm (Helium)

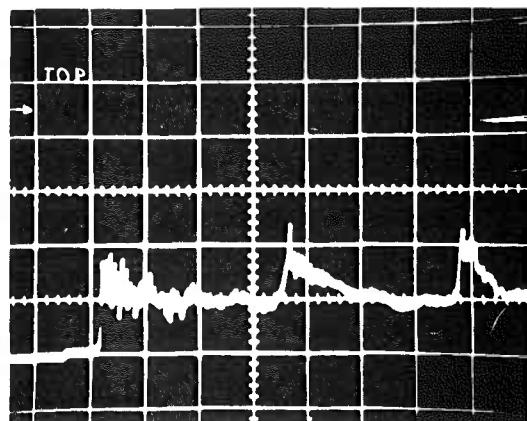
$P_1$  - 320 mm Hg (Air)

$P_8$  - 18  $\mu$  Hg (Air)

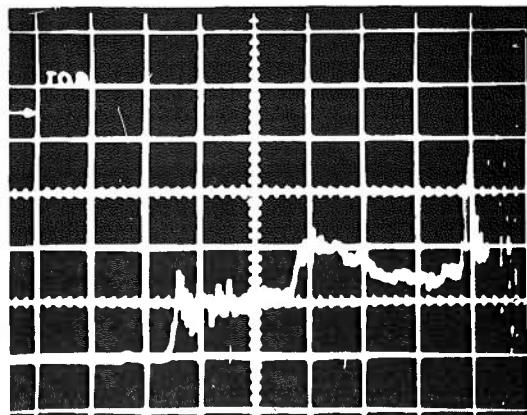
$M_{S8}$  - 11.5 to 7100

Sweep Rate - 100  $\mu$  sec/cm

Run 47  
 $l_8 = 46$



Run 48  
 $l_8 = 27.44$



Run 49  
 $l_8 = 17$

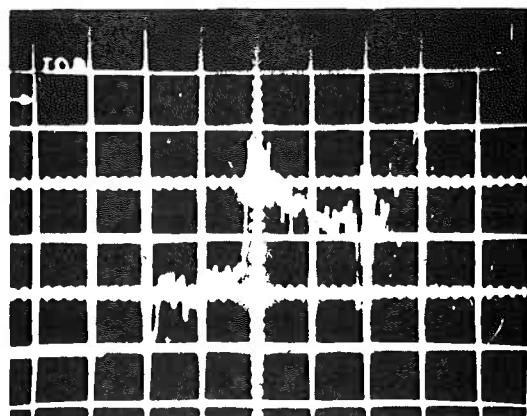


Fig. 17 Typical Traces for a Centerline Pitot Probe

$P_4$  - 1210 atm - Helium

$P_1$  - 310 mm Hg - Air

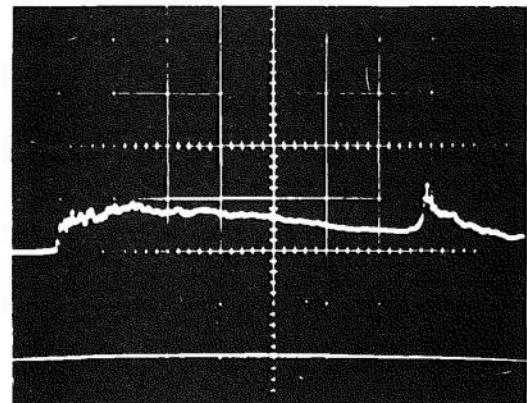
$P_8$  - 60  $\mu$  Hg 16% Air 84% Helium

Sweep Rate - 100  $\mu$  sec/cm

Vert. Sens.  $P_0'$  - 100 mv/cm

Note: Percent Composition  
by Volume

Run 99



Run 105

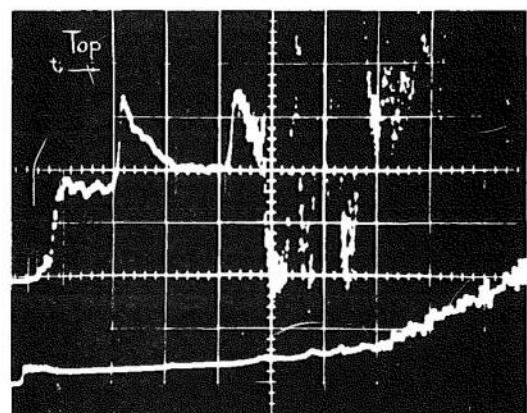
$P_4$  - 1520 atm - Helium

$P_1$  - 452 mm Hg - Air

$P_8$  - 40  $\mu$  Hg 25% Air 75% Helium

Sweep Rate - 200  $\mu$  sec/cm

Vert. Sens.  $P_0'$  - 50 mv/cm



Run 107

$P_4$  - 1480 atm - Helium

$P_1$  - 452 mm Hg - Air

$P_8$  - 100  $\mu$  Hg 10% Air 90% Helium

Sweep Rate - 200  $\mu$  sec/cm

Vert. Sens.  $P_0'$  - 50 mv/cm

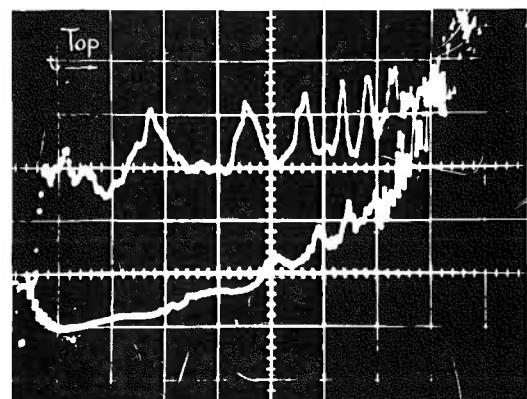


Fig. 18 Typical Pitot Traces for Helium-Air Mixture Accelerating  
Gas (Hemisphere-Cylinder Model)

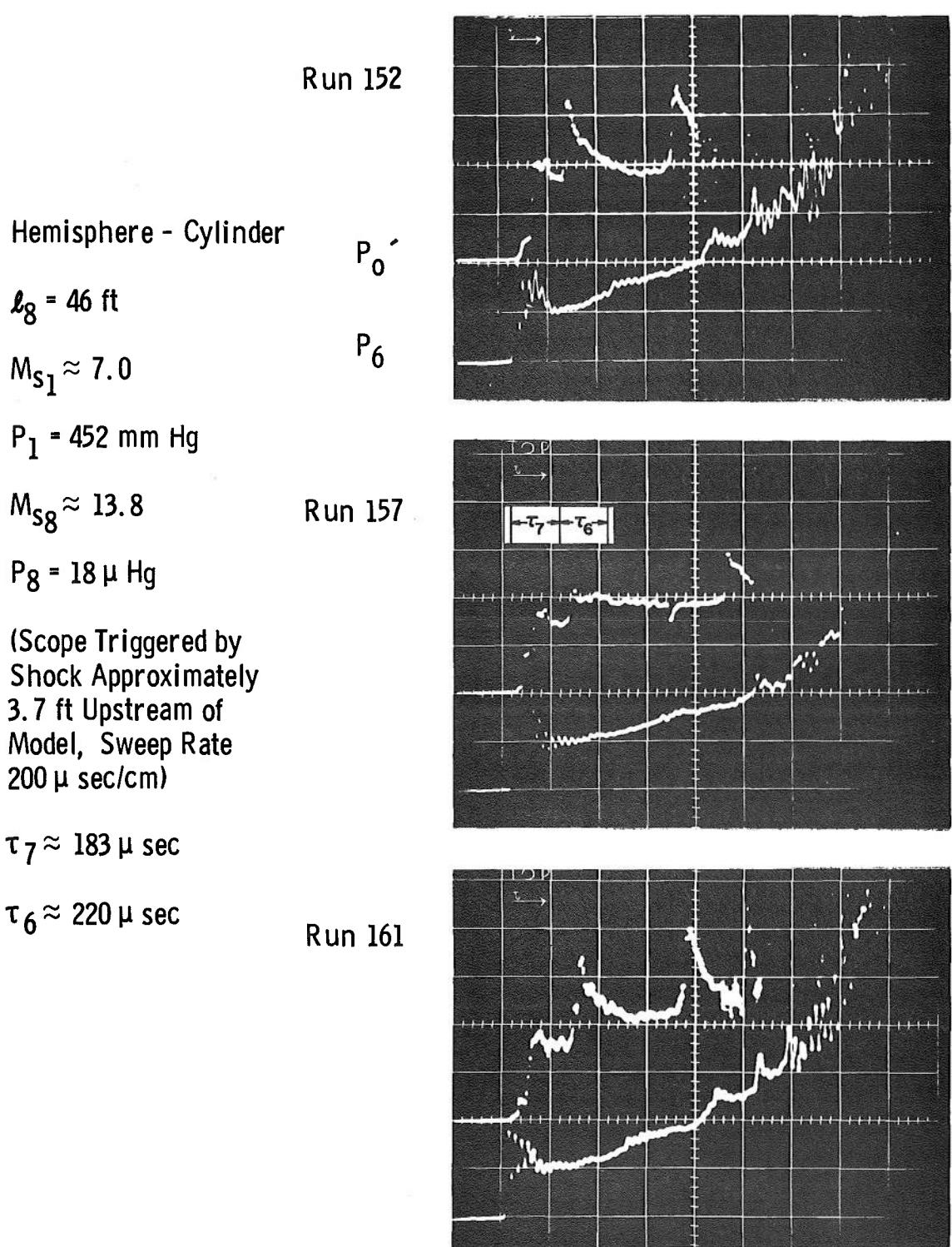


Fig. 19 Pitot and Static Pressure Traces,  $d_8 = 6.75$  in., One 3/4-mil Polyester

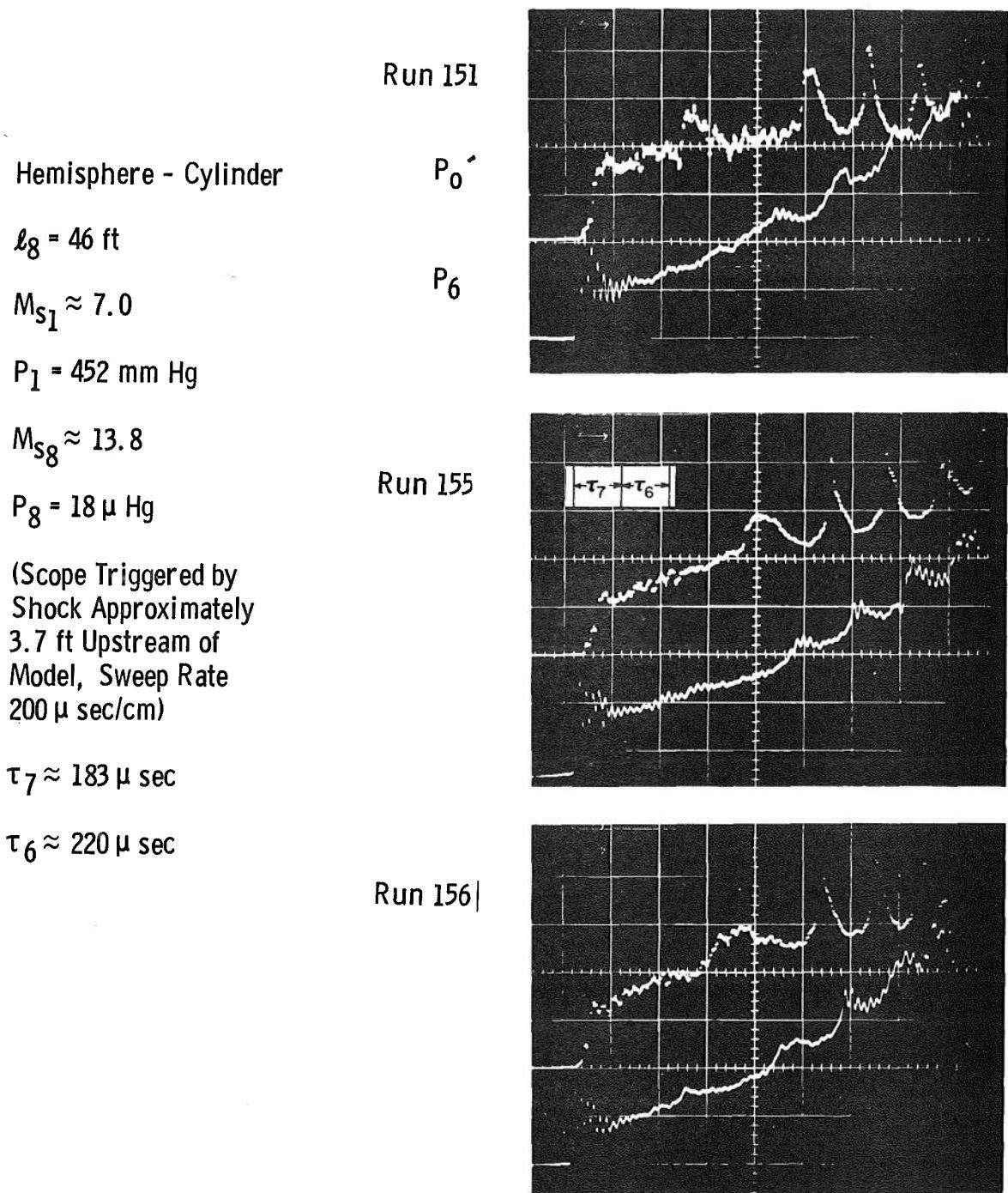


Fig. 20 Pitot and Static Pressure Traces,  $d_8 = 6.75$  in., One 3/4-mil Aluminum Foil

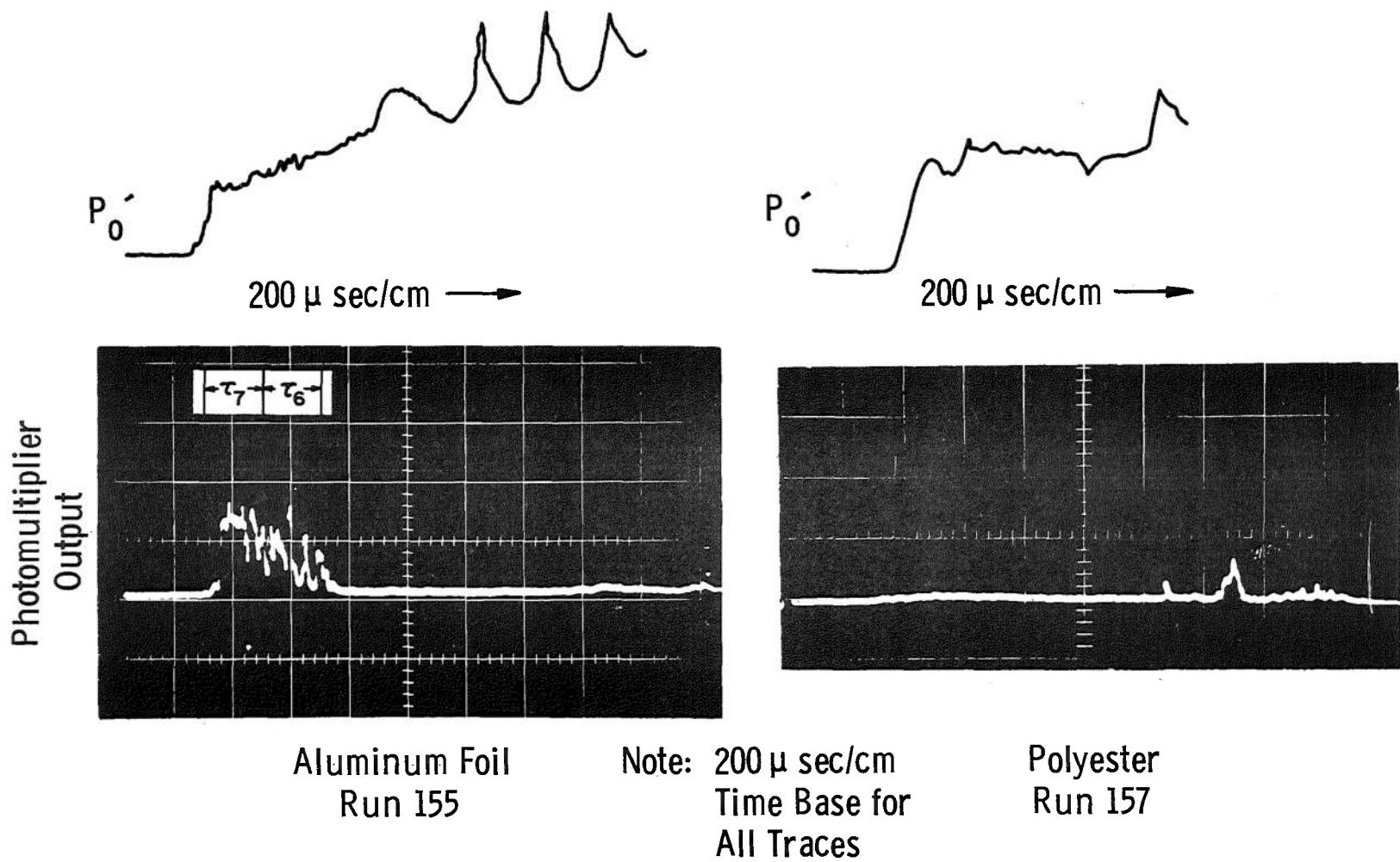
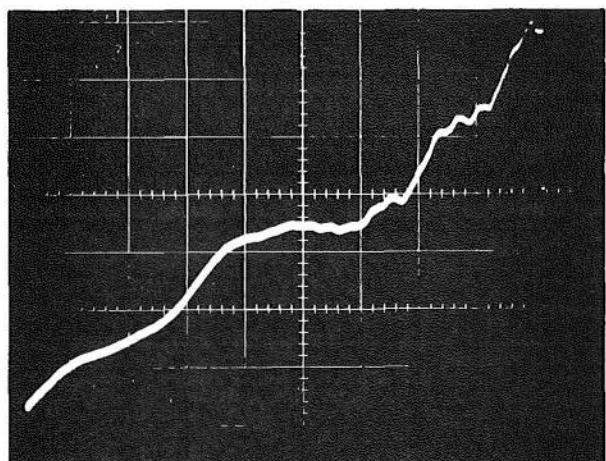


Fig. 21 Monochromatic ( $\approx 3090 \text{\AA}$ ) Radiation Using Aluminum Foil and Polyester Secondary Diaphragm

Run 180



$l_8 = 14.5$  ft

$M_{S1} \approx 7.4$

$P_1 = 544$  mm Hg (Air)

$M_{S8} \approx 18.0$

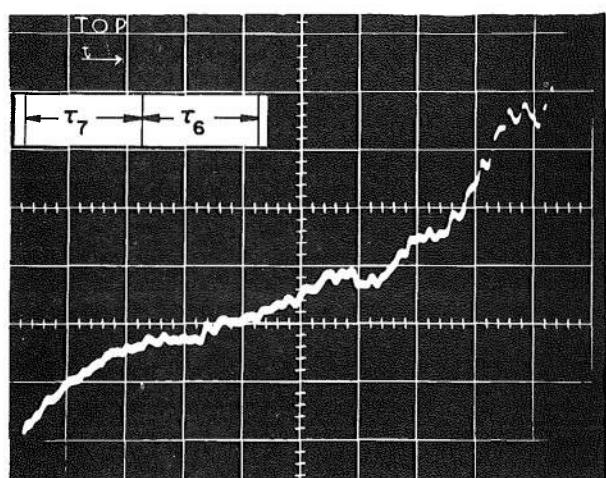
$P_8 = 18 \mu$  Hg (Air)

(Scope Triggered  
off Rise, Sweep  
Rate 20  $\mu$  sec/cm)

$\tau_7 \approx 42 \mu$  sec

$\tau_6 \approx 40 \mu$  sec

Run 182



Run 185

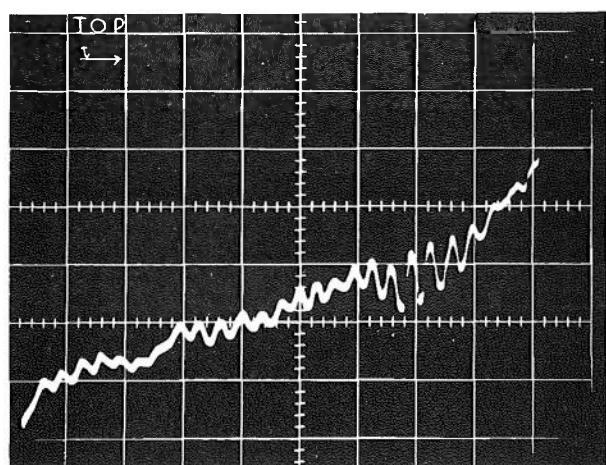
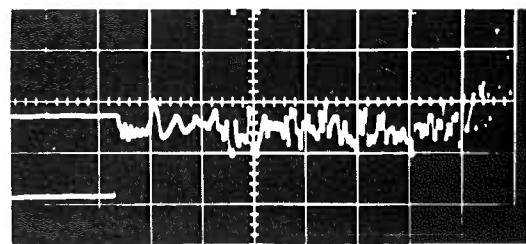
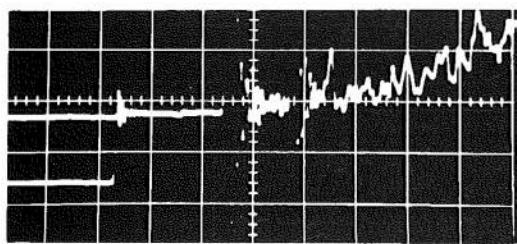
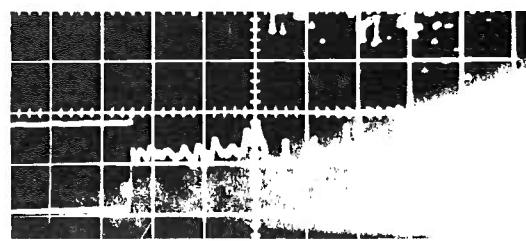
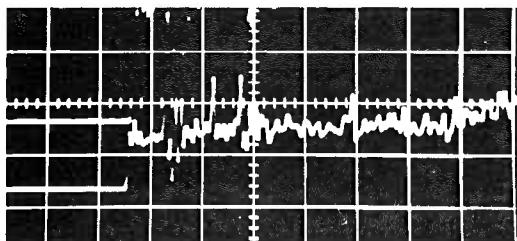


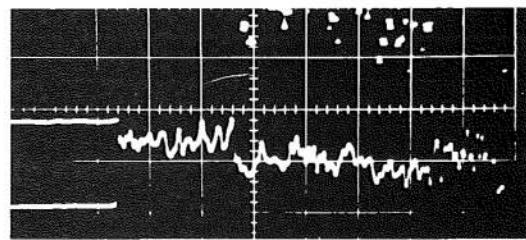
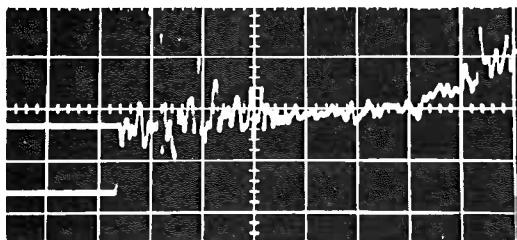
Fig. 22 Pitot Pressure Traces,  $d_8 = 1.60$  in., One 3/4-mil Polyester



Run 156

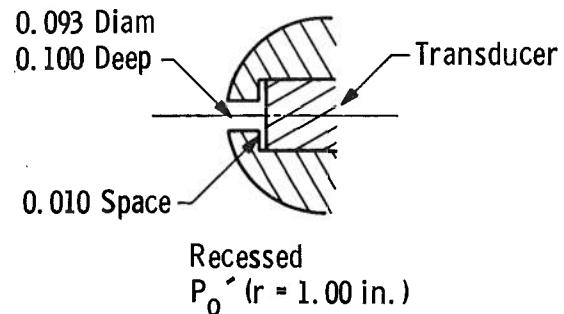
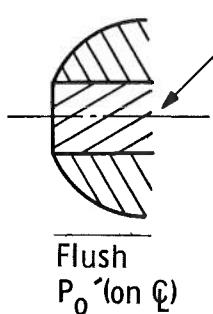


Run 158



Run 159

$M_{S1} \approx 5.5$   
 $P_1 = 251 \text{ mm Hg}$   
 Sweep Rate  $200 \mu \text{ sec/cm}$



Probe Details

Fig. 23 Comparison of Flush and Recessed Mounting of Pressure Transducer

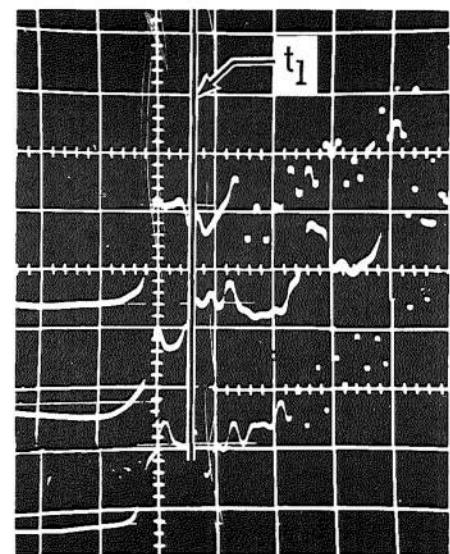
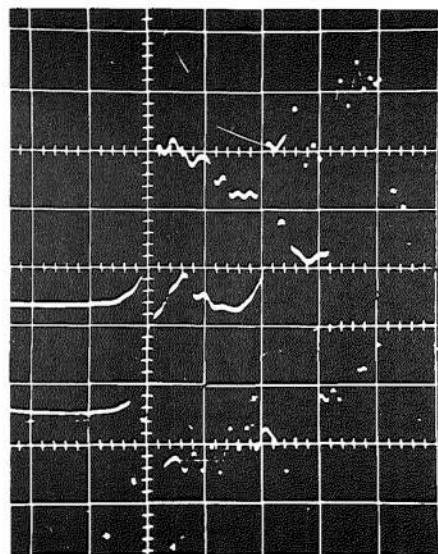
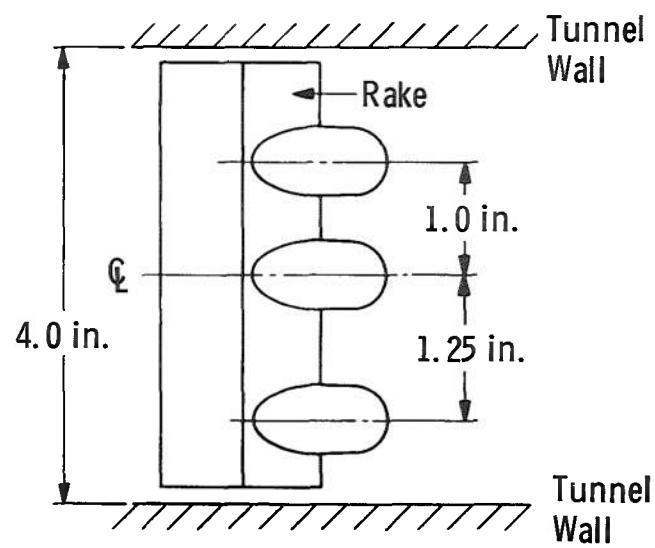
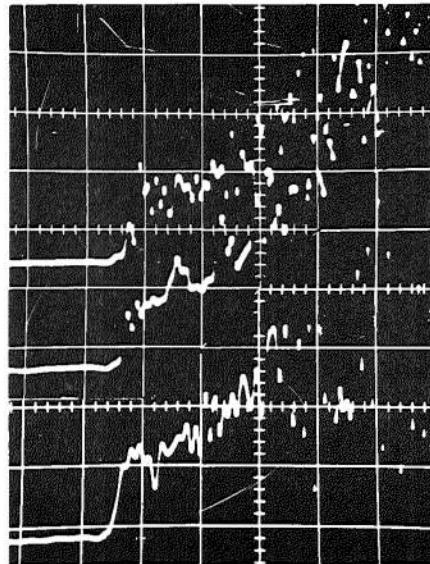
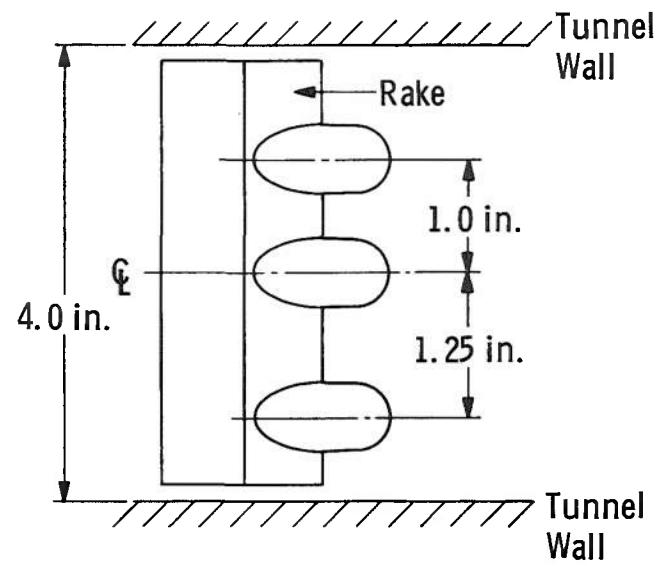
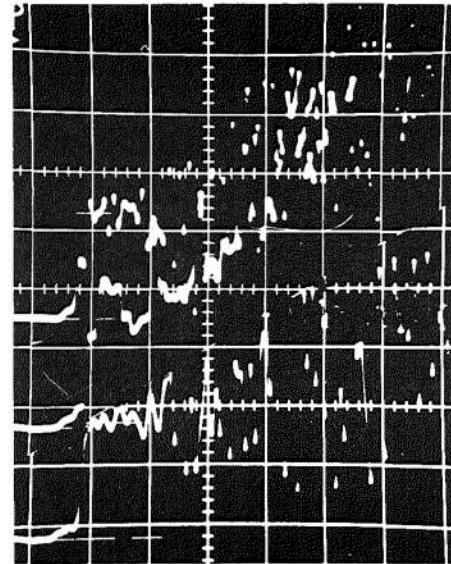


Fig. 24 Sketch of Rake and Sample Pitot Pressure Traces High Density Shock Tube,  $P_8 = 16 \mu\text{Hg}$



Run 119

Sweep Rate 100  $\mu$  sec/cm

Run 120

Sweep Rate 100  $\mu$  sec/cm

Fig. 25 Sketch of Rake and Sample Pitot Pressure Traces High Density Shock Tube,  $P_8 = 100 \mu\text{Hg}$

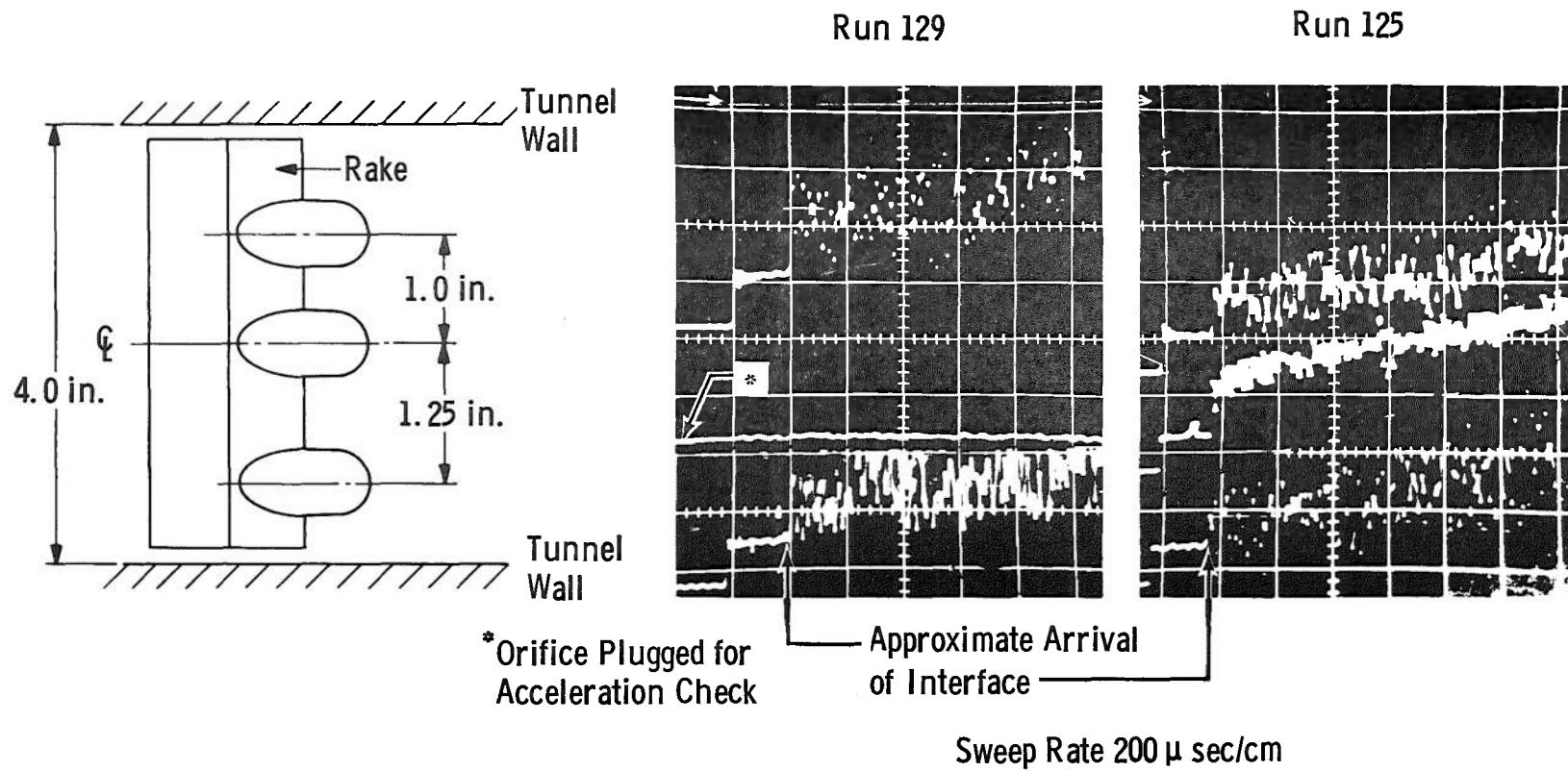


Fig. 26 Sketch of Rake and Sample Pitot Pressure Traces High Density Shock Tube,  $P_8 = 18 \text{ mm Hg}$

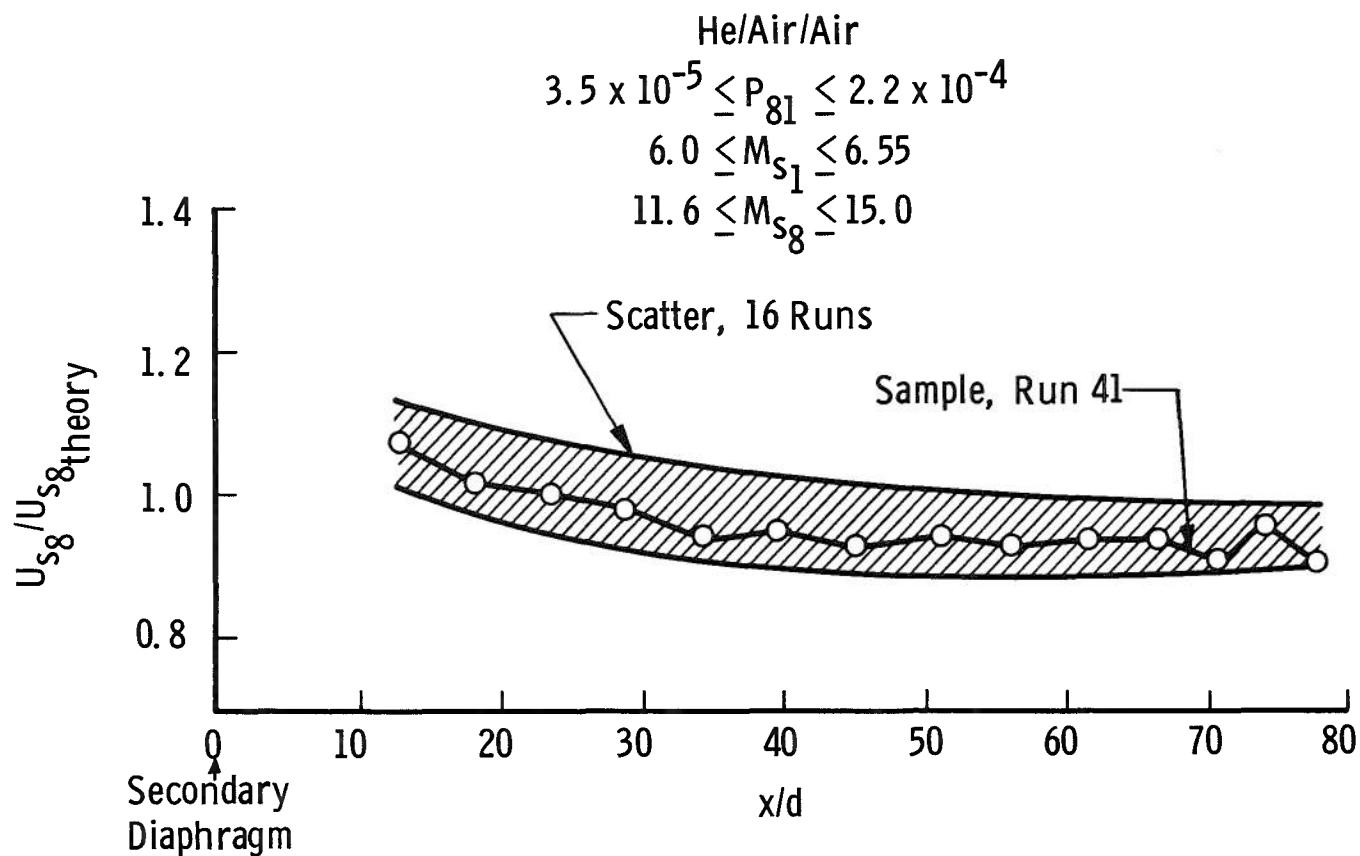


Fig. 27 Accelerating Tube Shock Velocity - Modified Expansion Tube

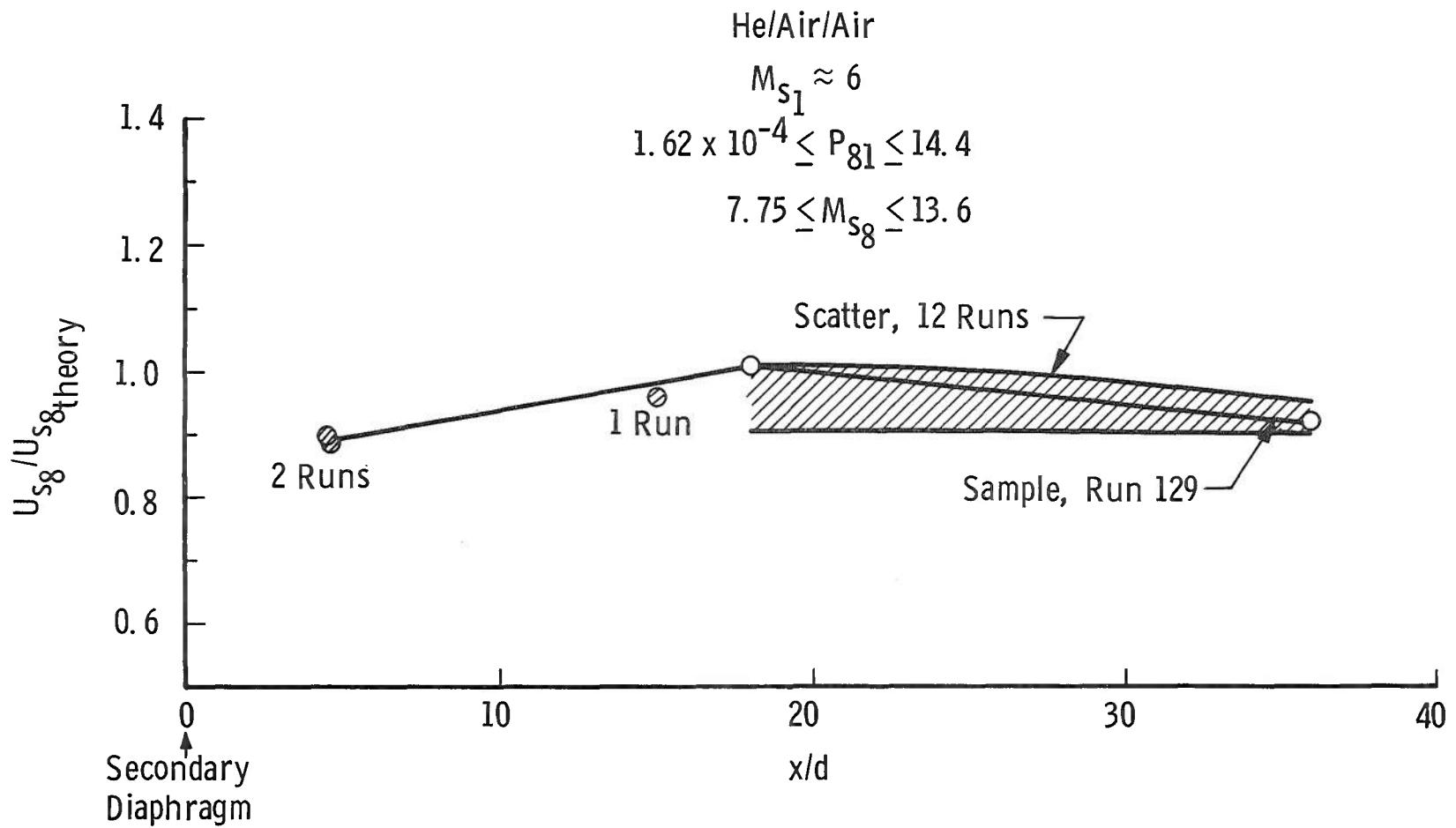


Fig. 28 Accelerating Tube Shock Velocity – High Density Shock Tube

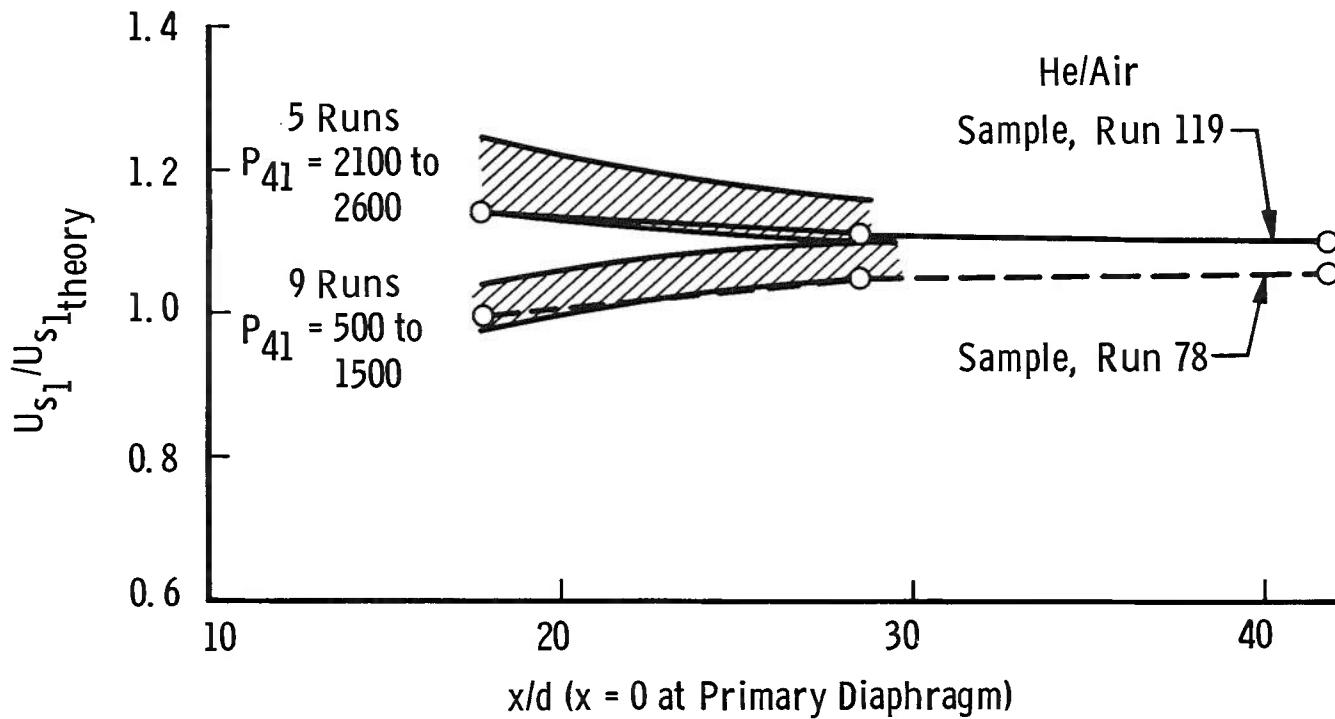


Fig. 29 Driven Tube Shock Velocity – Modified Expansion Tube

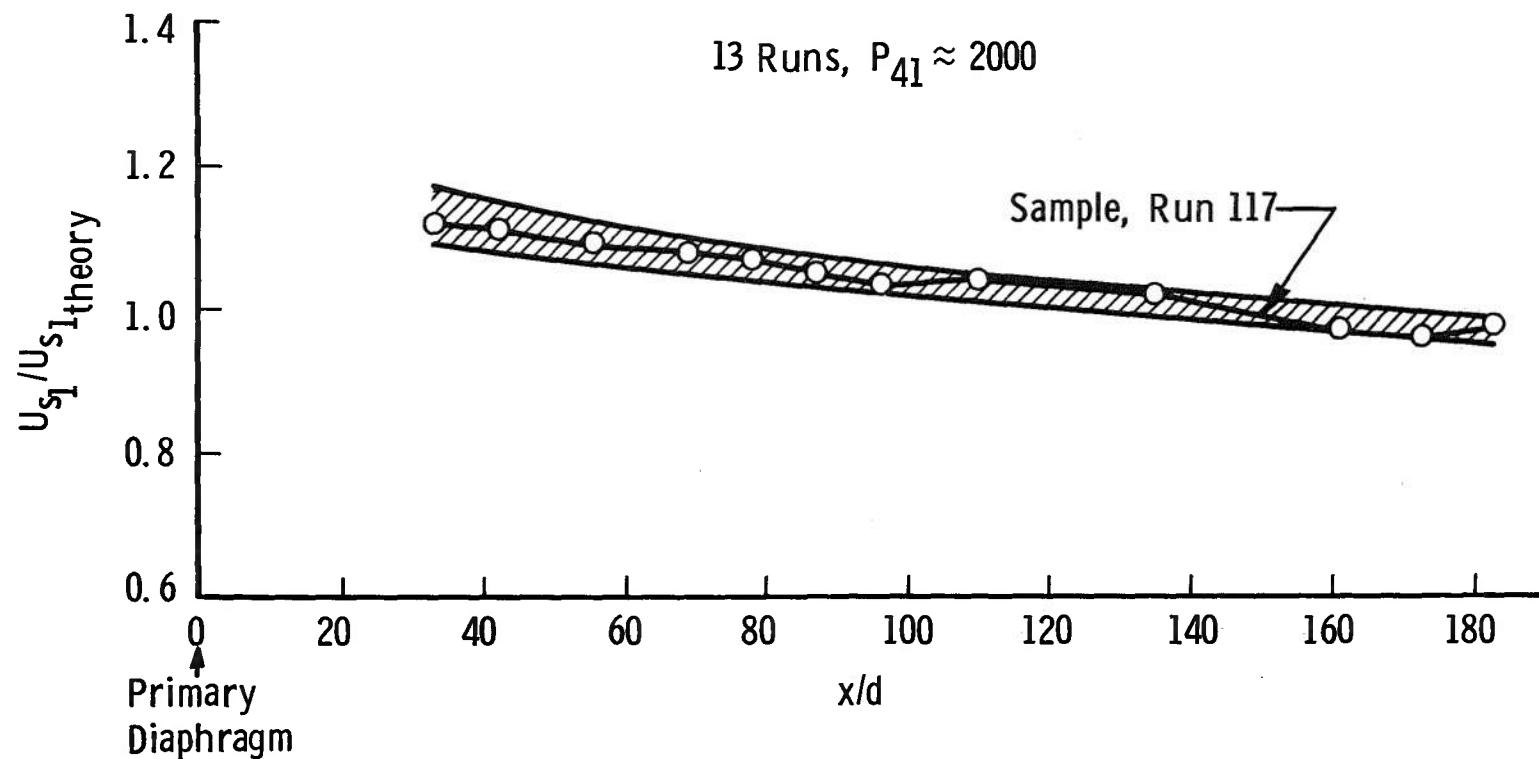


Fig. 30 Driven Tube Shock Velocity – High Density Shock Tube

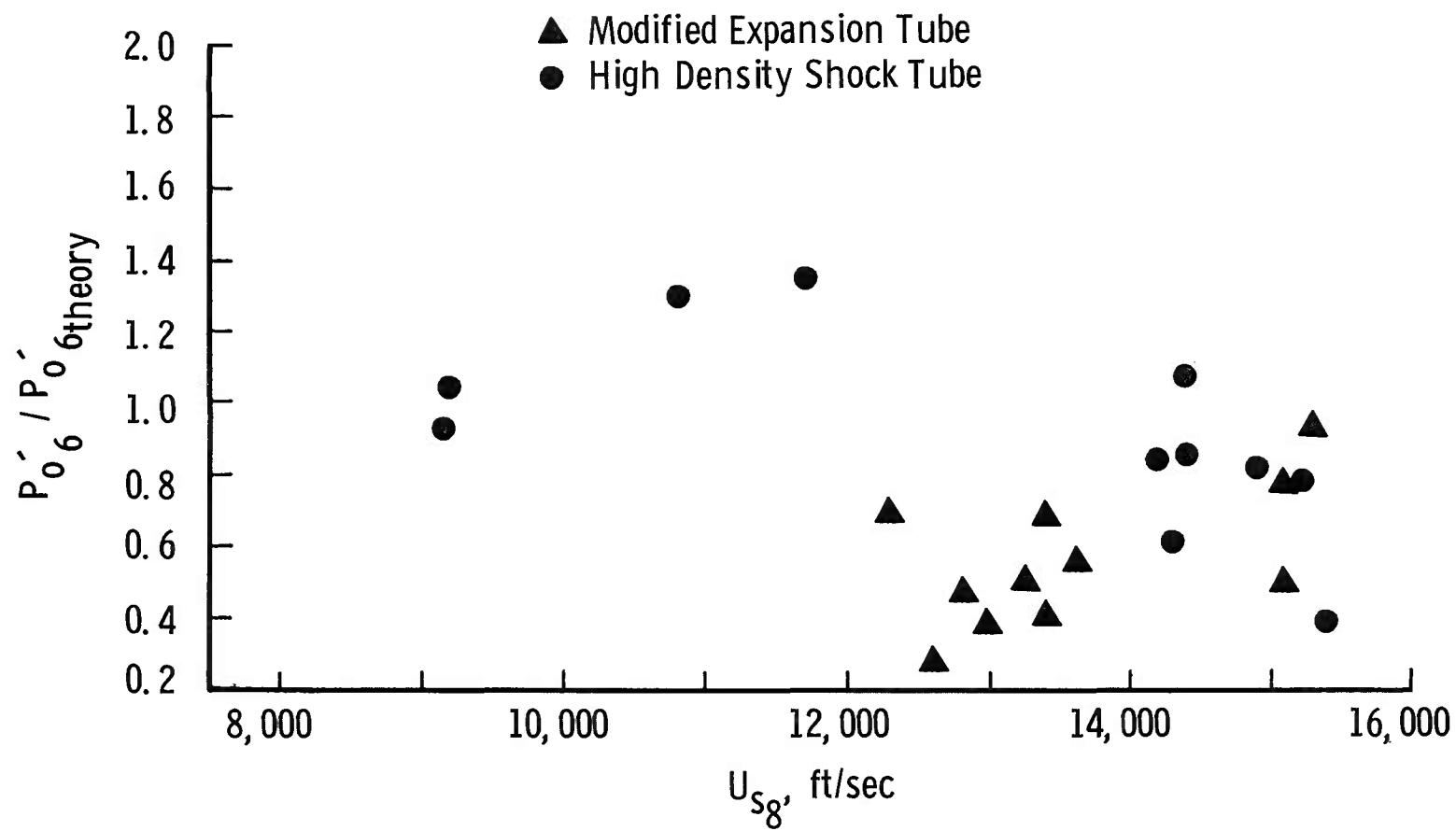


Fig. 31 Pitot Pressure at the Test Section

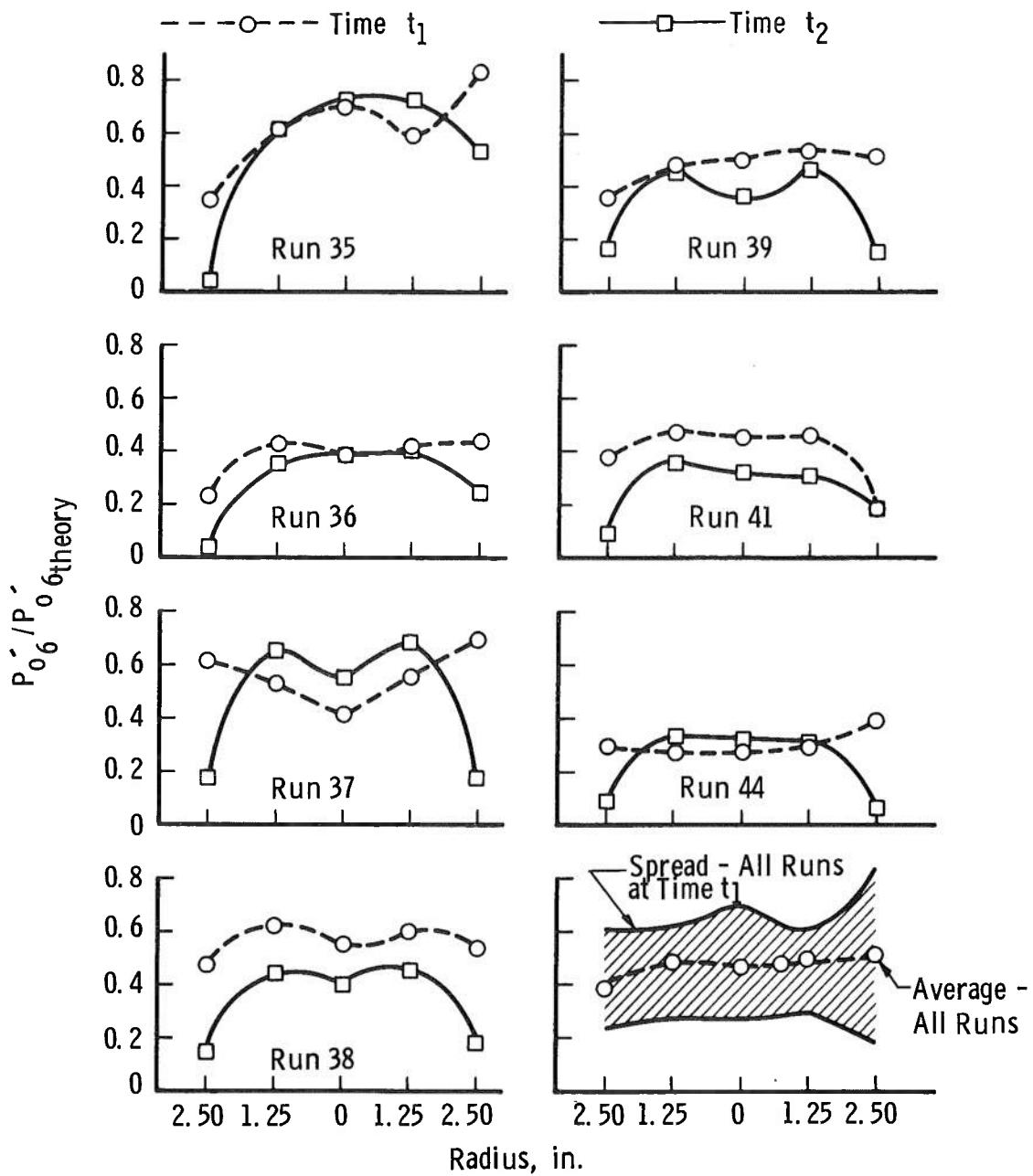


Fig. 32 Pitot Pressure Profile - Modified Expansion Tube

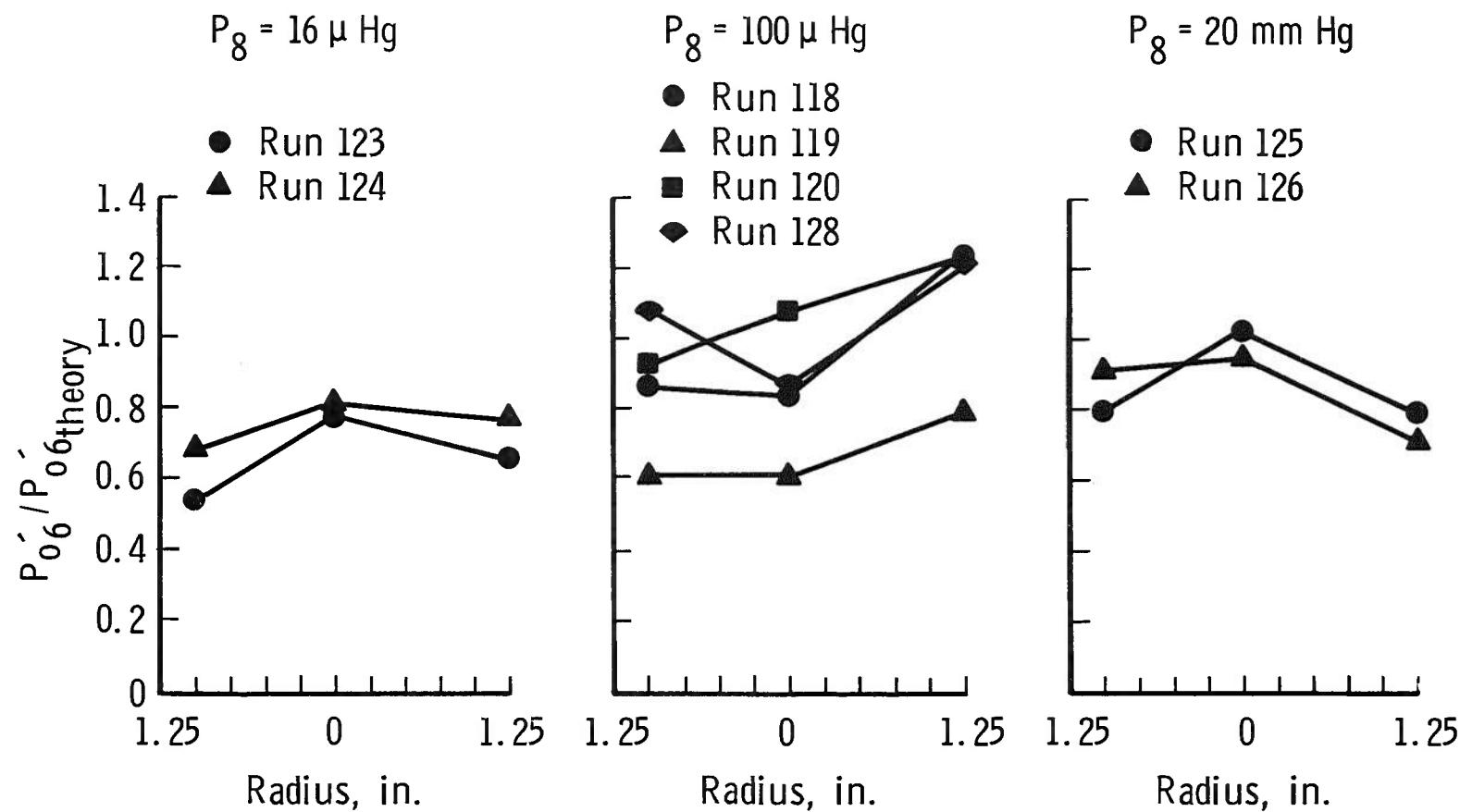
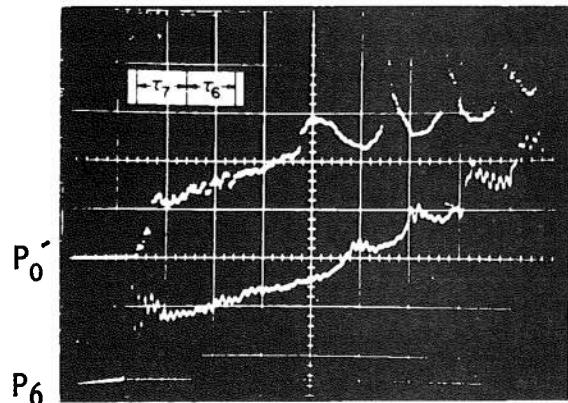
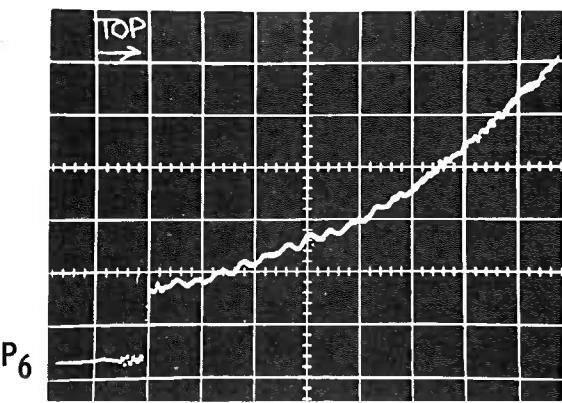


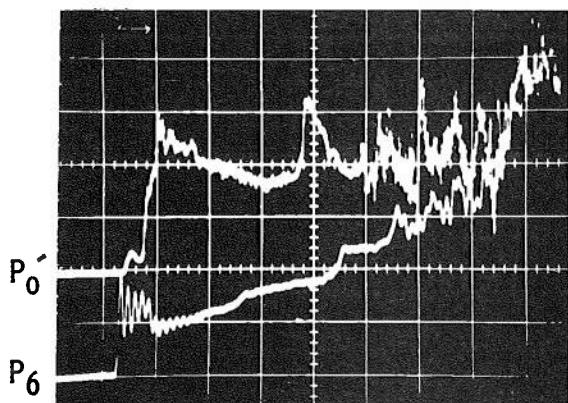
Fig. 33 Pitot Pressure Profile – High Density Shock Tube



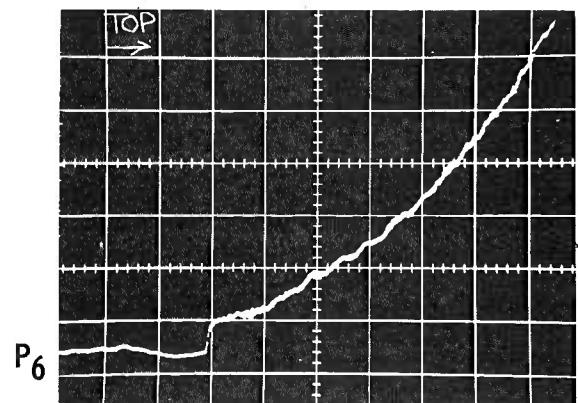
Run 155  
 $P_8 = 18 \mu\text{Hg}$



Run 126  
 $P_8 = 18 \text{ mm Hg}$



Run 153  
 $P_8 = 18 \mu\text{Hg}$



Run 114  
 $P_8 = 2.8 \text{ mm Hg}$

Modified Expansion Tube

High Density Shock Tube

Sweep Rate 200  $\mu\text{sec}/\text{cm}$

Fig. 34 Static Pressure Measurements

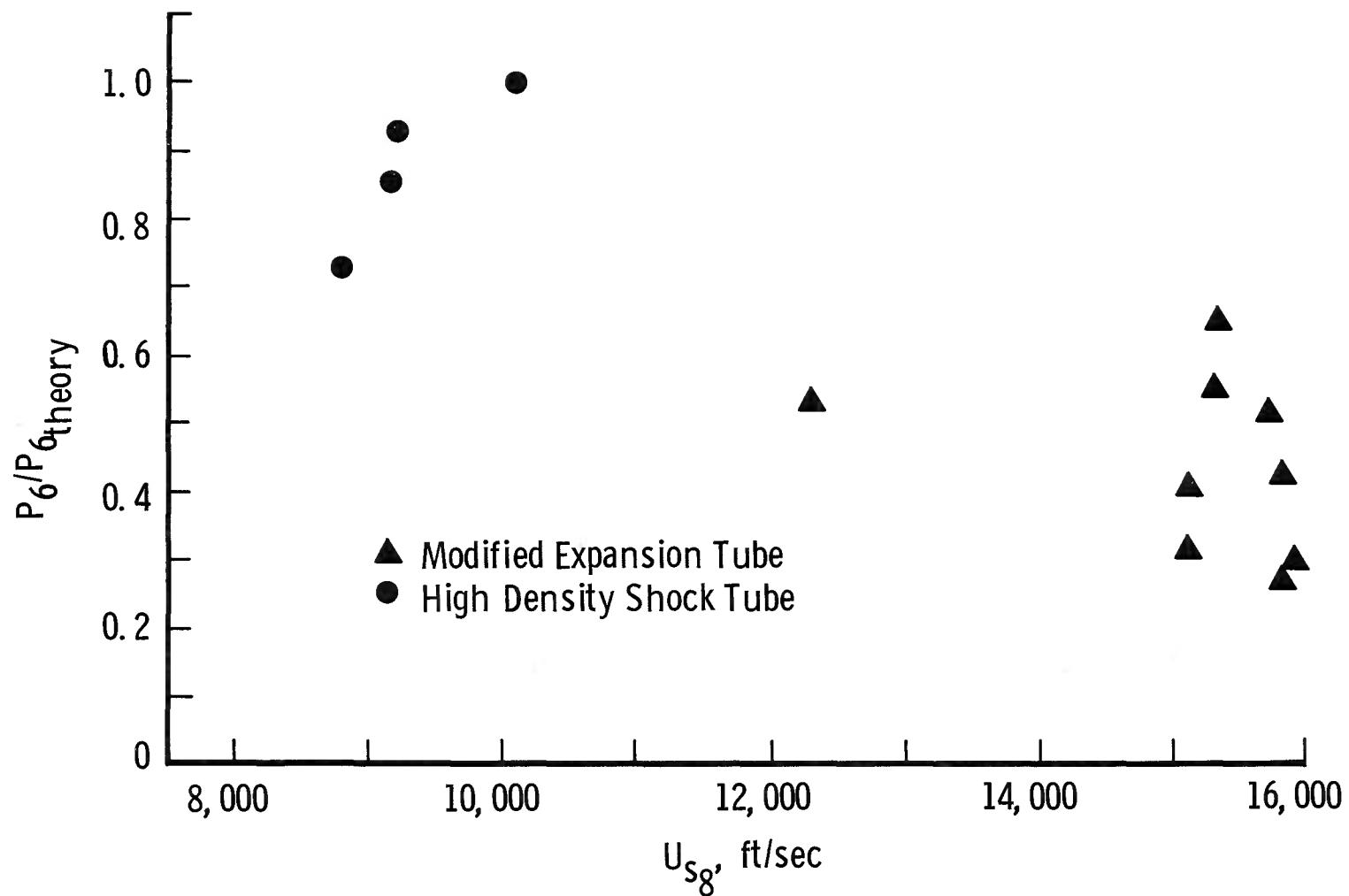


Fig. 35 Wall Static Pressure at the Test Section

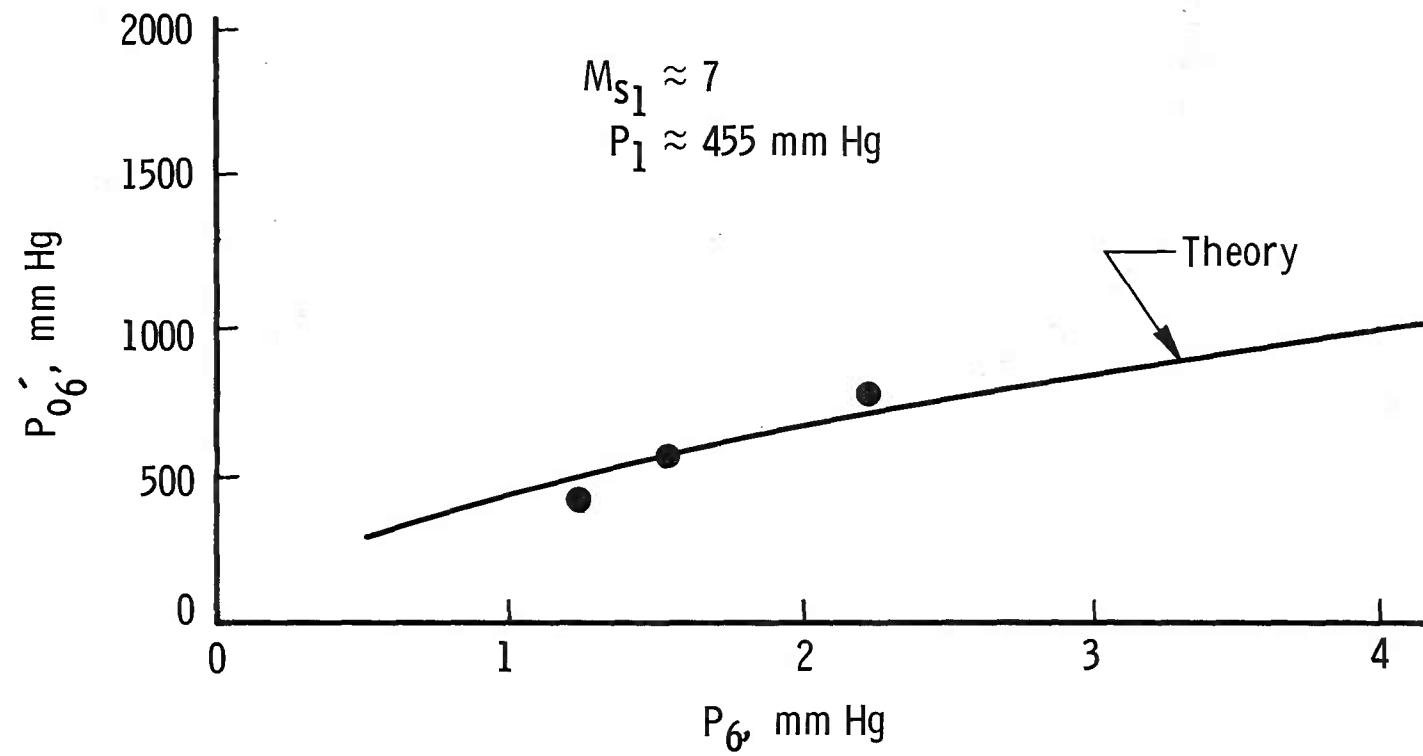


Fig. 36 Measured Pitot and Wall Static Pressure Compared with Theory-Modified Expansion Tube

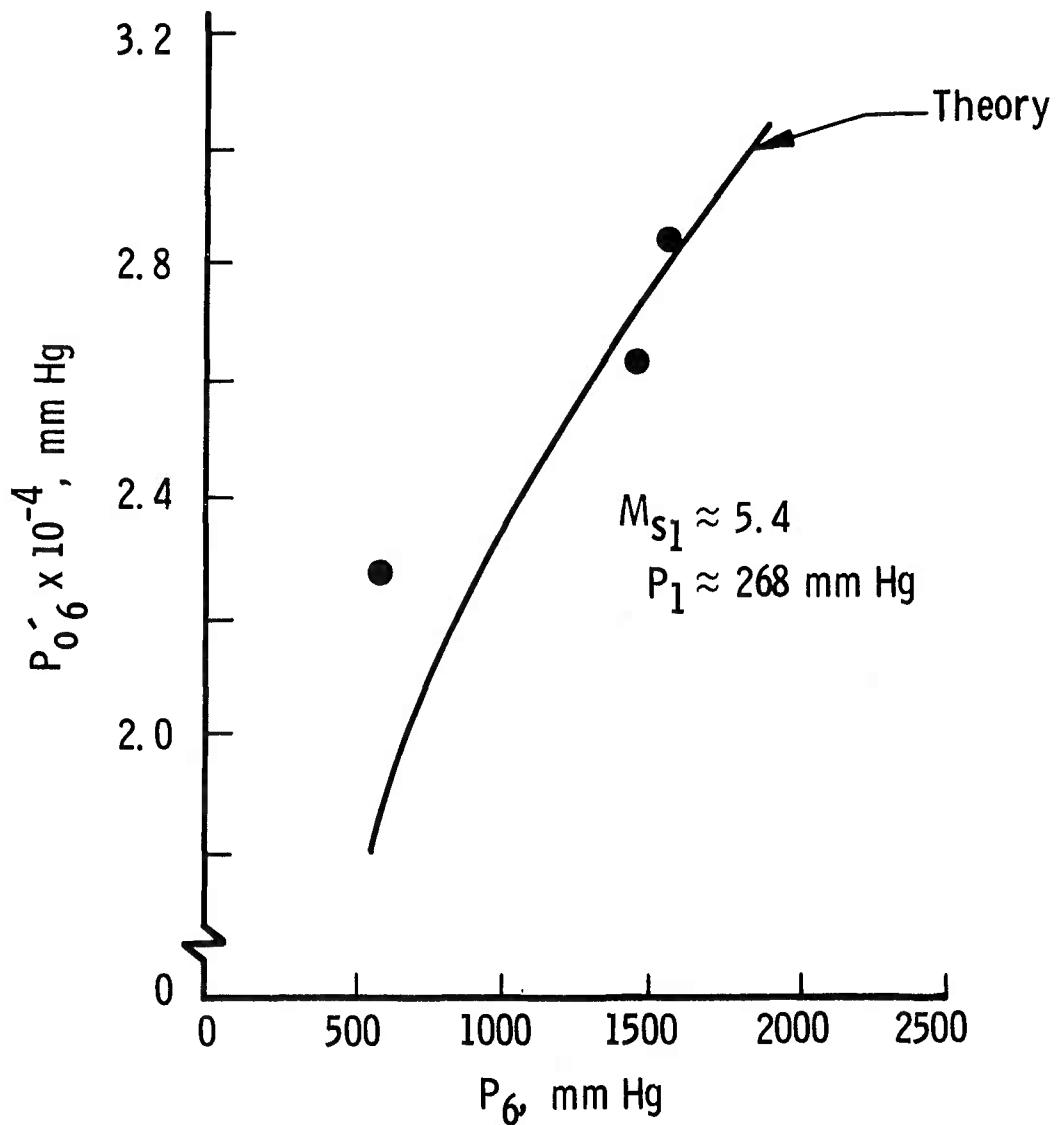


Fig. 37 Measured Pitot and Wall Static Pressure Compared with Theory - High Density Shock Tube

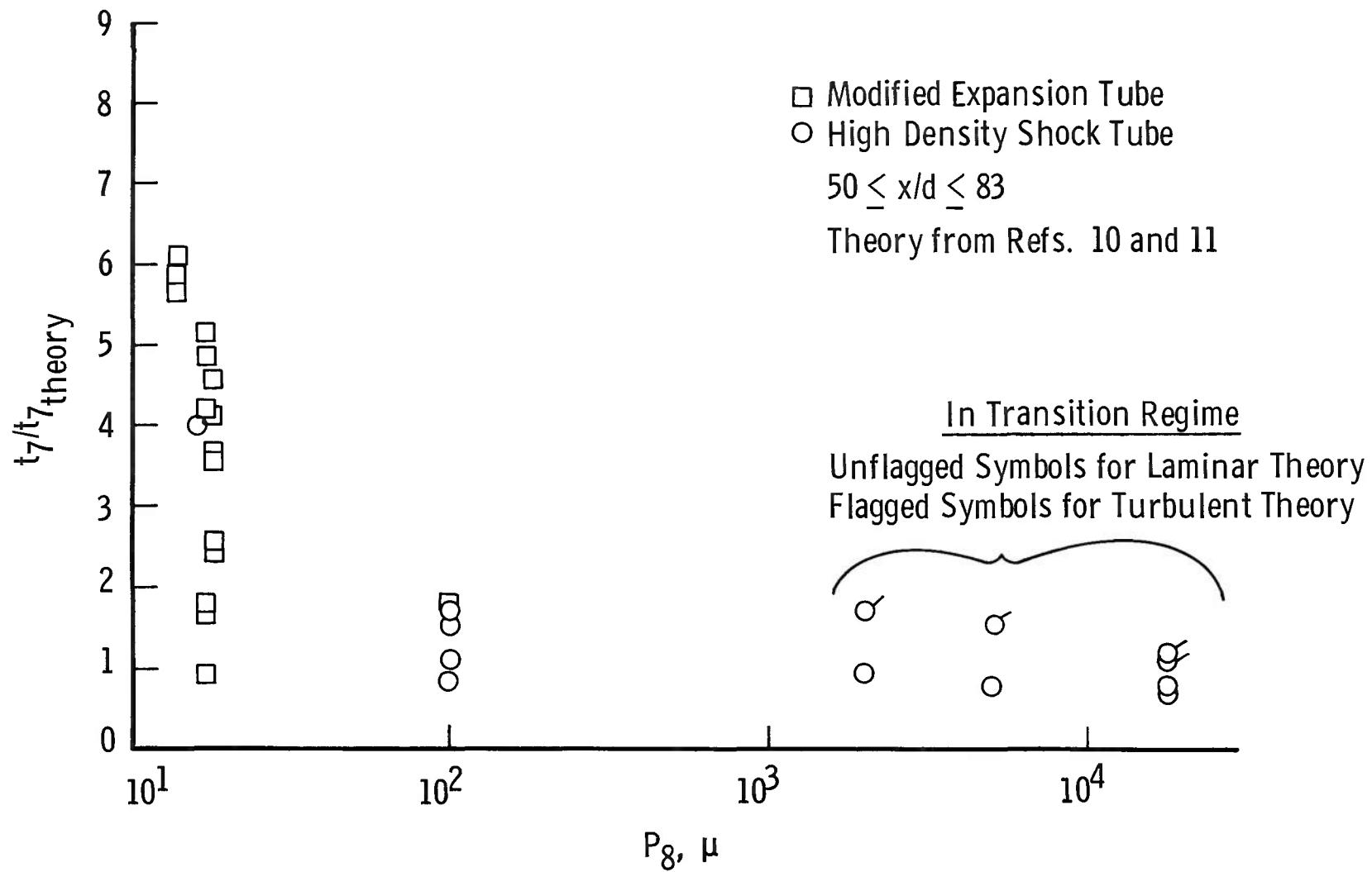


Fig. 38 Shock Heated Gas Passage Time,  $t_7$

$P_4 = 1300$  atm  
 $P_1 = 456$  mm Hg Air  
 $P_8 = 18 \mu$  Hg Air  
■ Estimated Accuracy

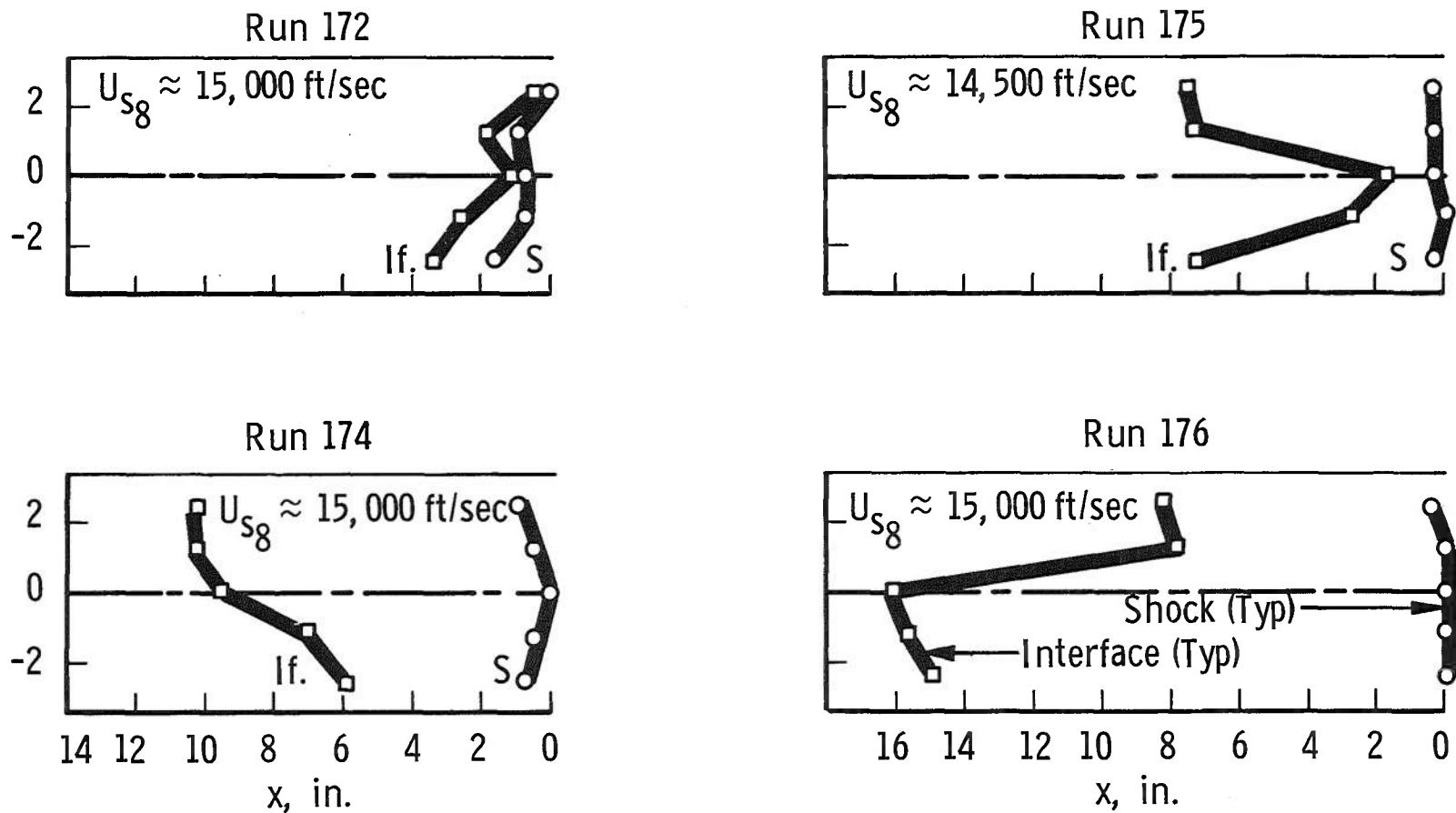


Fig. 39 Shock-Interface Separation

TABLE I  
INSTRUMENTATION

Measurement	Range	Strain-gage pressure transducer	Sensitivity	Rise Time	Filter	Readout	Est. Accuracy
I. $P_4$	5-25 K psi	Strain-gage pressure transducer	---	Steady state	---	Millivolt recorder	$\pm 10\%$
II. $P_1$	4-9 psia	Aneroid barometer	---	Steady state	---	Visual	$\pm 1\%$
III. $P_8$	$15\mu\text{Hg} - 5 \text{ psia}$	Thermocouple, McLeod and aneroid barometer	---	Steady state	---	Visual	$\pm 10\% \text{ or less}$
IV. $P_2$	100-500 psia	Piezoelectric	7 mv/psi	5 $\mu\text{sec}$	100 kc low pass	Oscilloscope	$\pm 10\%$
V. $P_6$	0.04-200 psia	Variable-capacitance and piezoelectric	500 mv/psi 7 mv/psi	15 $\mu\text{sec}$ 5 $\mu\text{sec}$	100 kc notch 100 kc low pass	Oscilloscope	$\pm 17\%$
VI. $P_{06}$	6-700 psia	Piezoelectric	7 mv/psi or 0.7 mv/psi	5 $\mu\text{sec}$	100 kc low pass	Oscilloscope	$\pm 12\%$
VII. $U_{S1}$ $U_{S8}$	5000-8000 fps 5000-16,000 fps	Platinum thin film	---	< 1 $\mu\text{sec}$	---	Raster Oscilloscope	$\pm 3\%$

TABLE II  
"SPIKE" HYPOTHESES

Hypothesis	Parameter	Variation
I. Mechanically induced accelerations	Model and model support system	All models of Fig. 11, single pitot probe supported from tube wall, pitot rake supported from "isolated" dump tank, sting length varied.
II. Instrumentation difficulties	Pressure transducer and associated circuitry	Instrumentation used in the centerline probe of pitot rake exchanged with that used in an off-center probe.
III. Flow instability on model	Model configuration	1.4-in. -diam. flat-face cylinder 0.3-in. -diam. flat-face probe 2-in. -diam. hemisphere-cylinder
IV. Oblique shock from wall	Longitudinal location of model	$18 \leq \ell_8 \leq 46$ ft
V. Accelerating tube viscous effects	Accelerating tube charge gas	$p_{He + Air} = \begin{cases} 30 \text{ Hg} \\ 40 \\ 60 \\ 100 \end{cases} \quad \left. \begin{array}{l} p_{air} = 10 \mu\text{Hg} \\ \hline \end{array} \right\}$
VI. Secondary diaphragm rupture effects	Secondary diaphragm thickness and material	1 and 2 1/4 mil polyester 1 to 8 3/4 mil polyester 1 1/4 mil aluminum coated polyester 1 3/4 mil aluminum foil
VII. Flow contamination by secondary diaphragm	(Same as VI)	(Same as VI)
VIII. Area change effect	Area ratio	$A_{81} = 1.0$ and 18.3

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Security Classification

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11. SUPPLEMENTARY NOTES <b>N/A</b>	12. SPONSORING MILITARY ACTIVITY Arnold Engineering Development Center, Air Force Systems Command, Arnold Air Force Station, Tenn.	
13. ABSTRACT  The results from an experimental study of an expansion tube conducted at the von Karman Gas Dynamics Facility (VGF) are presented and discussed. The research was conducted in two facilities: (1) a 6.75-in.-diam Modified Expansion Tube (MET) which utilizes a partially steady and partially unsteady expansion process, and (2) a 4-in.-diam (constant diameter) High Density Shock Tube (HDST) operated in an expansion tube mode for a completely unsteady expansion of the shock-heated gas to the final test condition. Flow velocities from approximately 9000 to 16,000 ft/sec were studied. The theoretical performance of expansion tubes in terms of velocity is found to be nearly obtained; however, the steadiness of the resulting flow leaves much to be desired, and the definition of accurate flow conditions remains in serious doubt.		

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	ROLE	WT	ROLE	WT	ROLE	WT
Expansion tubes Shock tubes Velocity Performance Pitot pressure Static pressure Hypervelocity flow Test devices						

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